- 8. The goal is to arrive at the least magnitude of \vec{F}_{net} , and as long as the magnitudes of \vec{F}_2 and \vec{F}_3 are (in total) less than or equal to $|\vec{F}_1|$ then we should orient them opposite to the direction of \vec{F}_1 (which is the +x direction).
 - (a) We orient both \vec{F}_2 and \vec{F}_3 in the -x direction. Then, the magnitude of the net force is 50-30-20 = 0, resulting in zero acceleration for the tire.
 - (b) We again orient \vec{F}_2 and \vec{F}_3 in the negative x direction. We obtain an acceleration along the +x axis with magnitude

$$a = \frac{F_1 - F_2 - F_3}{m} = \frac{50 \text{ N} - 30 \text{ N} - 10 \text{ N}}{12 \text{ kg}} = 0.83 \text{ m/s}^2.$$

(c) In this case, the forces \vec{F}_2 and \vec{F}_3 are collectively strong enough to have y components (one positive and one negative) which cancel each other and still have enough x contributions (in the -x direction) to cancel \vec{F}_1 . Since $|\vec{F}_2| = |\vec{F}_3|$, we see that the angle above the -x axis to one of them should equal the angle below the -x axis to the other one (we denote this angle θ). We require

$$-50 \text{ N} = \vec{F}_{2x} + \vec{F}_{3x}$$
$$= -(30 \text{ N}) \cos \theta - (30 \text{ N}) \cos \theta$$

which leads to

$$\theta = \cos^{-1} \left(\frac{50 \,\mathrm{N}}{60 \,\mathrm{N}} \right) = 34^\circ \ .$$