# THE KERNEL ABSTRACTION

#### Challenge: Protection

- How do we execute code with restricted privileges?
  - Either because the code is buggy or if it might be malicious

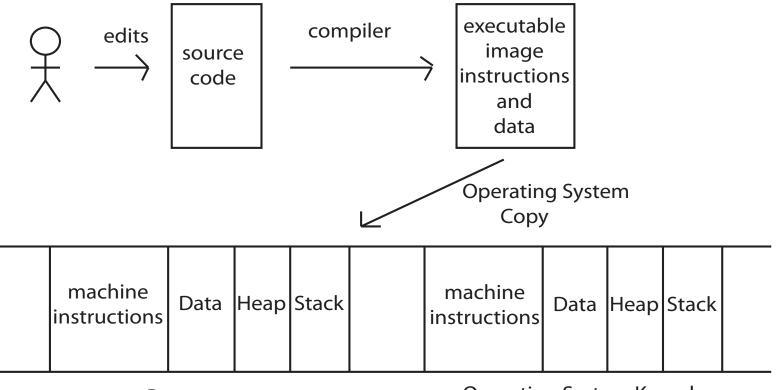
#### Some examples:

- A script running in a web browser
- A program you just downloaded off the Internet
- A program you just wrote that you haven't tested yet

#### Main Points

- Process concept
  - A process is an OS abstraction for executing a program with limited privileges
- Dual-mode operation: user vs. kernel
  - Kernel-mode: execute with complete privileges
  - User-mode: execute with fewer privileges
- Safe control transfer
  - How do we switch from one mode to the other?

#### **Process Concept**



Process

**Operating System Kernel** 

**Physical Memory** 

#### **Process Concept**

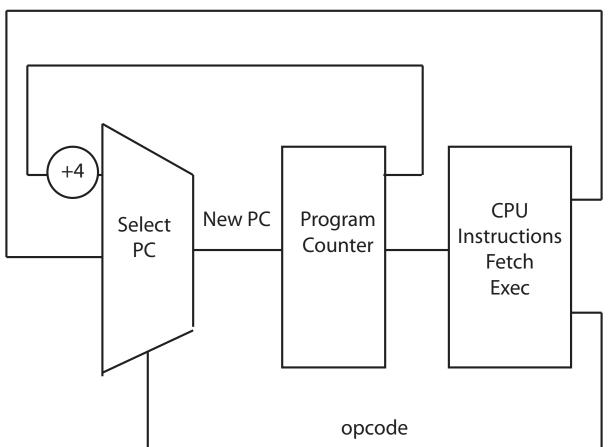
- Process: an instance of a program, running with limited rights
  - Process control block: the data structure the OS uses to keep track of a process
  - Two parts to a process:
    - Thread: a sequence of instructions within a process
      - Potentially many threads per process (for now 1:1)
      - Thread aka lightweight process
    - Address space: set of rights of a process
      - Memory that the process can access
      - Other permissions the process has (e.g., which procedure calls it can make, what files it can access)

#### Hardware Support: Dual-Mode Operation

- Kernel mode
  - Execution with the full privileges of the hardware
  - Read/write to any memory, access any I/O device, read/write any disk sector, send/read any packet
- User mode
  - Limited privileges
  - Only those granted by the operating system kernel
- On the x86, mode stored in EFLAGS register

#### A Model of a CPU

**Branch Address** 



#### A CPU with Dual-Mode Operation

**Branch Address** +4CPU New PC Program Instructions Handler Select Counter PC Fetch PC Exec New Select Mode Mode Mode opcode

#### Hardware Support: Dual-Mode Operation

- Privileged instructions
  - Available to kernel
  - Not available to user code
- Limits on memory accesses
  - To prevent user code from overwriting the kernel
- Timer
  - To regain control from a user program in a loop
- Safe way to switch from user mode to kernel mode, and vice versa

۲

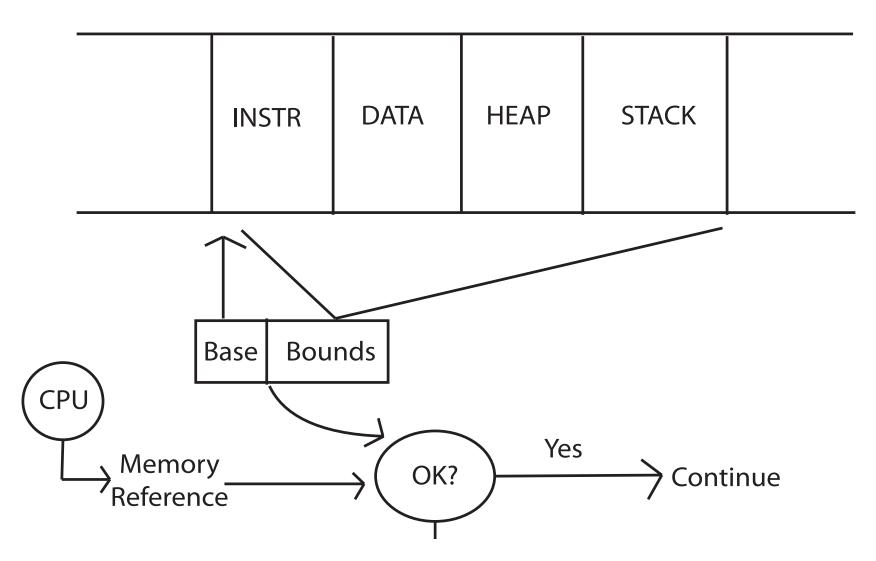
. . .

#### **Privileged instructions**

- Examples?
  - Change the execution mode
  - Access memory positions it has no permission to
  - Input/Output operations
  - Jump into kernel code
  - Enable/disable interrupts

- What should happen if a user program attempts to execute a privileged instruction?
  - Processor exception

#### **Memory Protection**

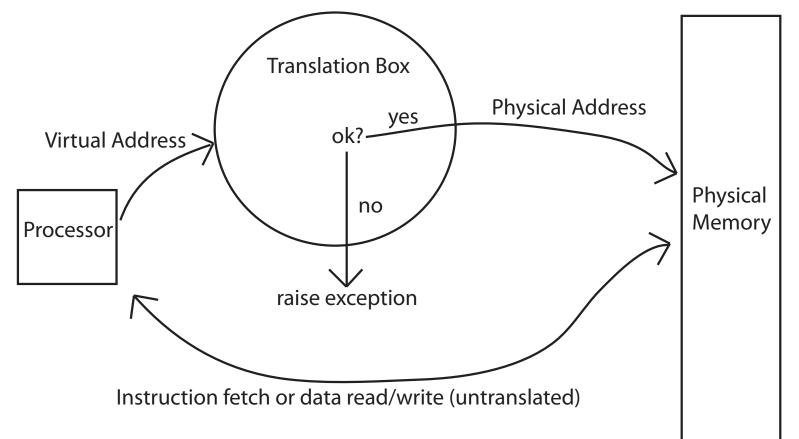


#### **Towards Virtual Addresses**

- Problems with base and bounds?
  - Expandable heap?
  - Expandable stack?
  - Memory sharing between processes?
  - Non-relative addresses hard to move memory around
  - Memory fragmentation

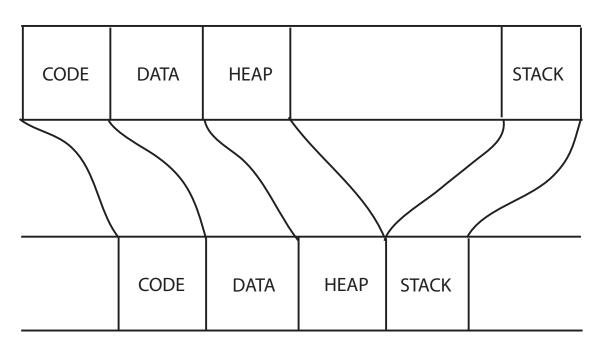
#### Virtual Addresses

- Translation done in hardware, using a table
- Table set up by operating system kernel



#### Virtual Address Layout

 Plus shared code segments, dynamically linked libraries, memory mapped files, …

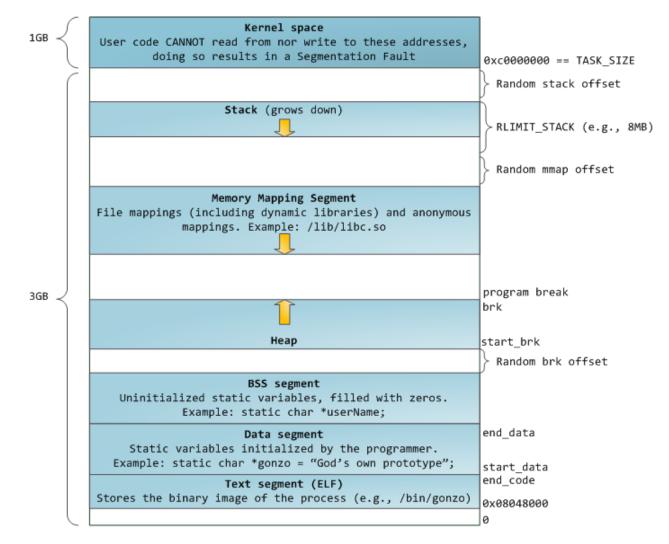


Virtual Addresses (Process Layout)

**Physical Memory** 

#### Process Memory Map (Linux)

taken from http://duartes.org/gustavo/blog/post/anatomy-of-a-program-in-memory/



15

#### Example: What Does this Do?

```
int staticVar = 0; // a static variable
int main() {
    int localVar = 0; // a procedure local variable
    staticVar += 1; localVar += 1;
    sleep(10); // sleep causes the program to wait for x seconds
    printf ("static address: %x, value: %d\n", &staticVar, staticVar);
    printf ("procedure local address: %x, value: %d\n", &localVar,
    localVar);
}
```

Produces:

```
static address: 5328, value: 1 procedure local address: ffffffe2, value: 1
```

#### Hardware Timer

- Hardware device that periodically interrupts the processor
  - Returns control to the kernel timer interrupt handler
  - Interrupt frequency set by the kernel
    - Not by user code!
  - Interrupts can be temporarily deferred
    - Not by user code!
    - Crucial for implementing mutual exclusion

#### Mode Switch

- From user-mode to kernel
  - Interrupts
    - Triggered by timer and I/O devices
  - Exceptions
    - Triggered by unexpected program behavior
    - Or malicious behavior!
  - System calls (aka protected procedure call)
    - Request by program for kernel to do some operation on its behalf
    - Only limited # of very carefully coded entry points

#### Mode Switch

- From kernel-mode to user
  - New process/new thread start
    - Jump to first instruction in program/thread
  - Return from interrupt, exception, system call
    - Resume suspended execution
  - Process/thread context switch
    - Resume some other process
  - User-level upcall
    - Asynchronous notification to user program

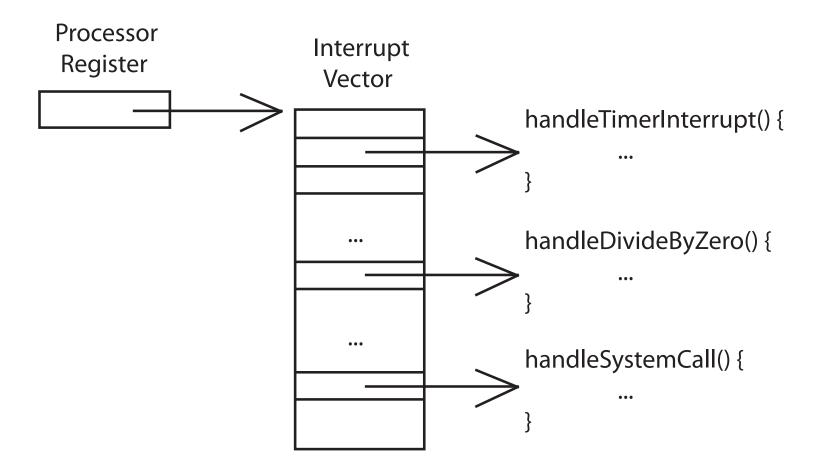
#### How do we take interrupts safely?

- Limited number of entry points into kernel
  - Interrupt vector
- Handler works regardless of state of user code
  - Kernel interrupt stack
- Handler is non-blocking
  - Interrupt masking

- Atomic transfer of control
  - Single instruction to change:
    - Program counter
    - Stack pointer
    - Memory protection
    - Kernel/user mode
- User program does not know interrupt occurred
  - Transparent restartable execution

#### **Interrupt Vector**

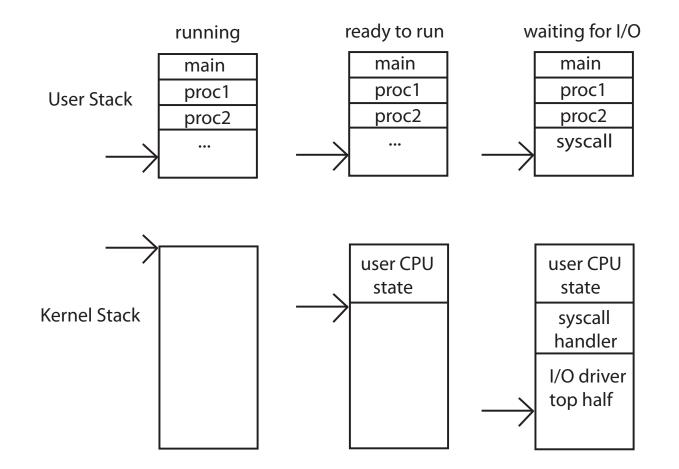
 Table set up by OS kernel; pointers to code to run on different events



#### Interrupt Stack

- Per-processor, located in kernel (not user) memory
  - Usually a thread has both: kernel and user stack
- Why can't interrupt handler run on the stack of the interrupted user process?
  - Process' stack pointer may be corrupted
  - Prevent other threads to access/modify kernel internal information

#### **Interrupt Stack**



23

### **Interrupt Masking**

- Interrupt handler runs with interrupts off
  - Reenabled when interrupt completes
- OS kernel can also turn interrupts off
  - Eg., when determining the next process/thread to run
  - If defer interrupts too long, can drop I/O events
  - On x86
    - CLI: disable interrrupts
    - STI: enable interrupts
    - Only applies to the current CPU
- Cf. implementing synchronization, chapter 5

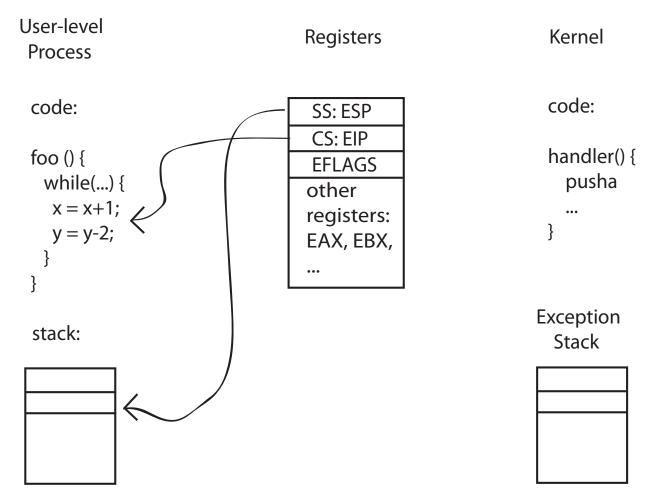
#### **Interrupt Handlers**

- Non-blocking, run to completion
  - Minimum necessary to allow device to take next interrupt
  - Any waiting must be limited duration
  - Wake up other threads to do any real work
- Rest of device driver runs as a kernel thread
  - Queues work for interrupt handler
  - (Sometimes) wait for interrupt to occur

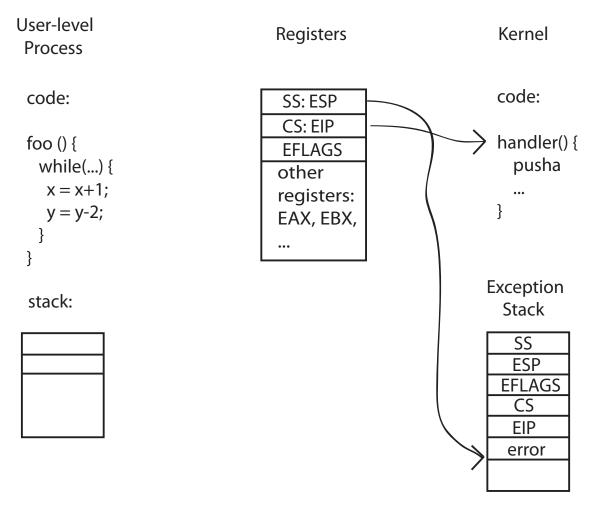
#### Atomic Mode Transfer

- On interrupt (x86)
  - Save current stack pointer
  - Save current program counter
  - Save current processor status word (condition codes)
  - Switch to kernel stack; put SP, PC, PSW on stack
  - Switch to kernel mode
  - Vector through interrupt table
  - Interrupt handler saves registers it might clobber

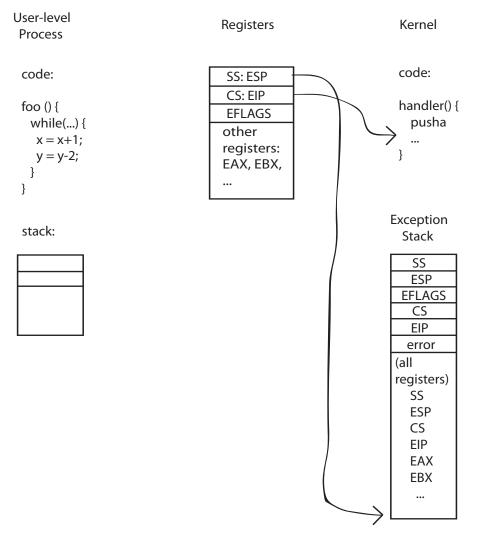
#### The x86 Example Before Interrupt



#### The x86 Example Upon Interrupt Reception



#### The x86 Example During the Handler's Execution

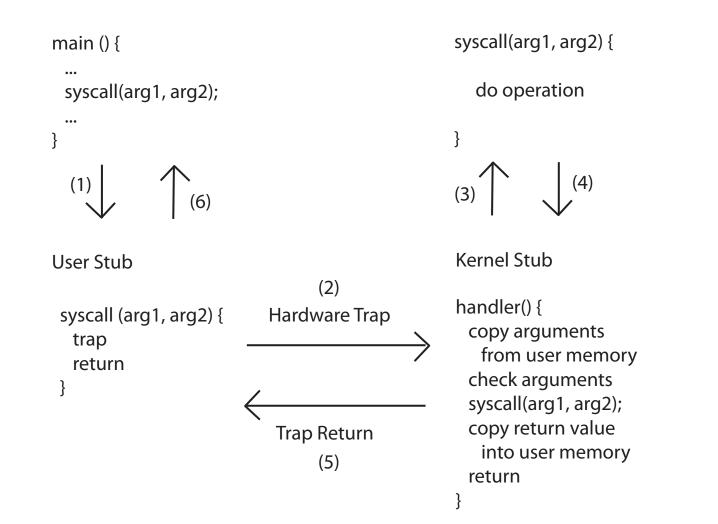


#### At end of handler

- Handler restores saved registers
- Atomically return to interrupted process/thread
  - Restore program counter
  - Restore program stack
  - Restore processor status word/condition codes
  - Switch to user mode

## System Calls



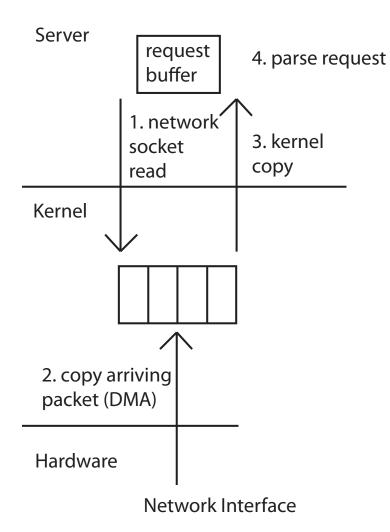


Kernel

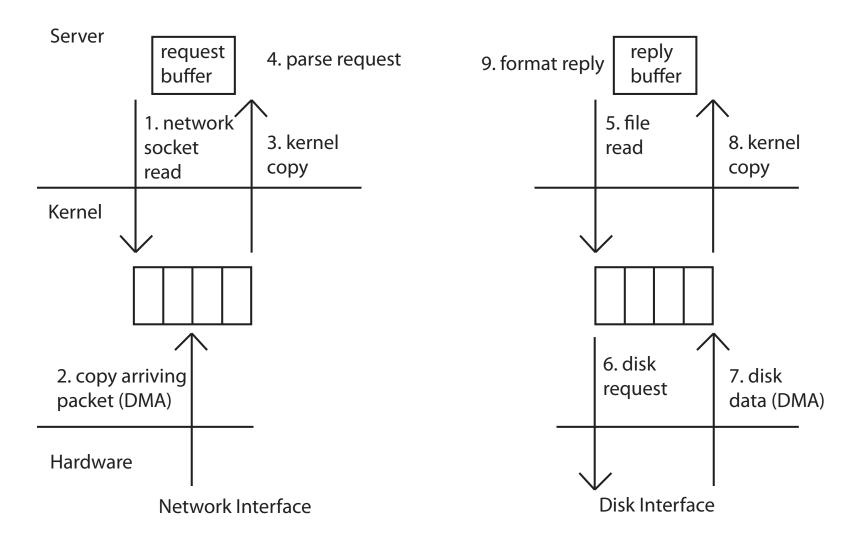
### Kernel System Call Handler

- Locate arguments
  - In registers or on user(!) stack
- Copy arguments
  - From user memory into kernel memory
  - Protect kernel from malicious code evading checks
- Validate arguments
  - Protect kernel from errors in user code
- Copy results back
  - into user memory

### Web Server Example

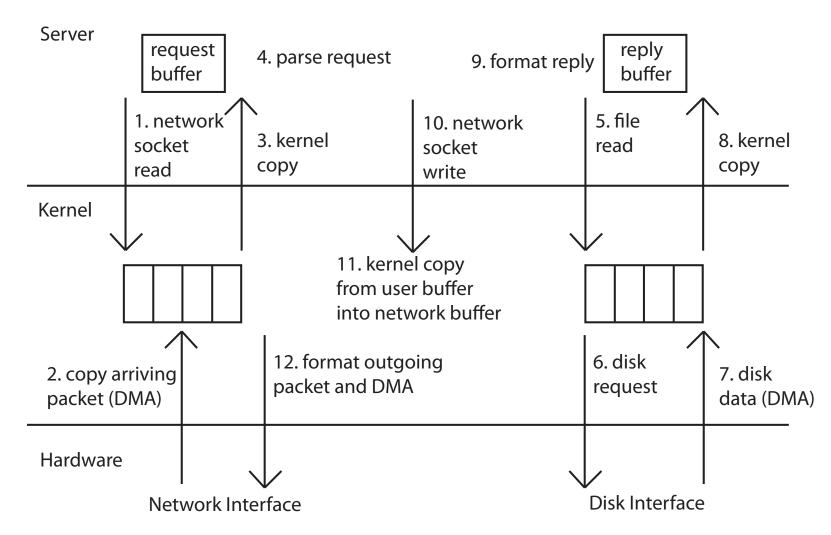


#### Web Server Example



34

#### Web Server Example



#### **New Process**

- Create process
  - 1. Allocate and initialize the process control block (PCB)
  - 2. Allocate memory for the process
  - 3. Copy the program from disk into the newly allocated memory
  - 4. Allocate a user-level stack
  - 5. Allocate a kernel-level stack
- Run process
  - 1. Copy arguments into user memory
  - 2. Transfer control to user mode

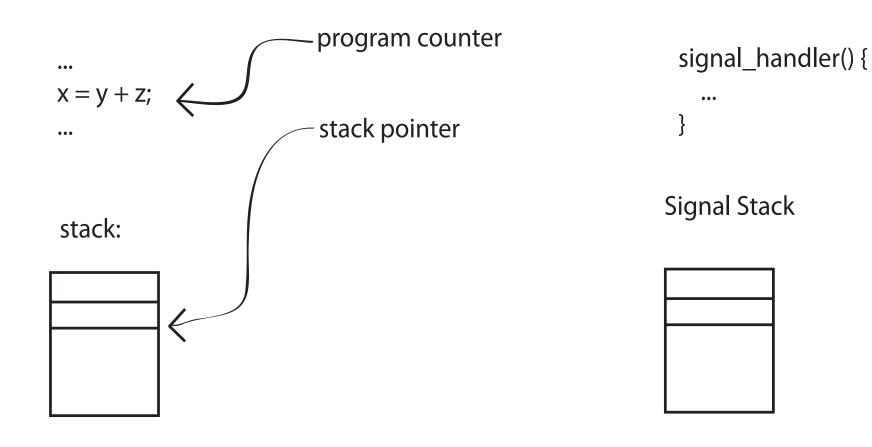
### Upcall: User-level interrupt

- AKA UNIX signal
  - Notify user process of event that needs to be handled right away
- Use-cases:
  - Preemptive user-level threads
  - Asynchronous I/O notification
  - Interprocess communication
  - User-level exception handling
  - User-level resource allocation

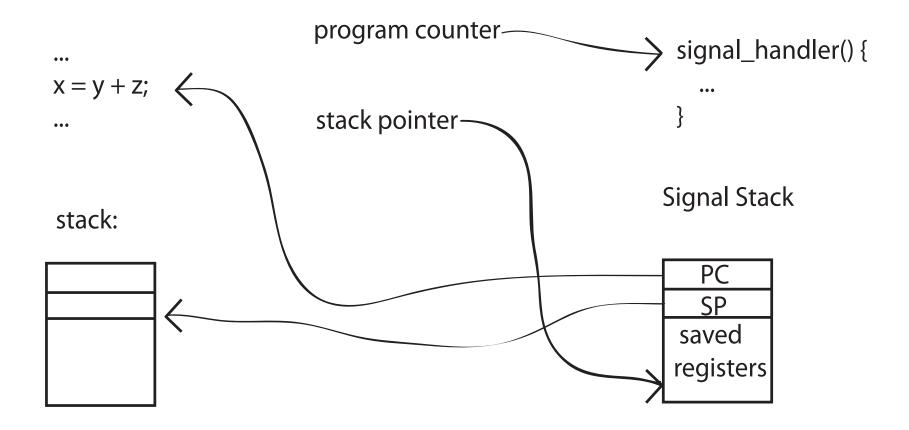
#### Upcall: User-level interrupt

- Direct analogue of kernel interrupts
  - Signal handlers fixed entry points
  - Separate signal stack
  - Automatic save/restore registers transparent resume
  - Signal masking: signals disabled while in signal handler

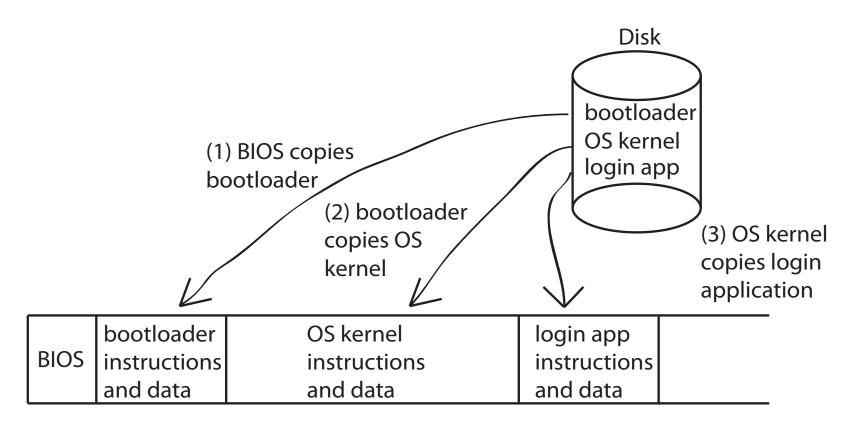
#### Upcall Example Before a Unix signal



#### Upcall Example During a Unix signal handling



# Booting



**Physical Memory**