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# Concurrency Errors (4)

lecture 24 (2020-05-26)

**Master in Computer Science and Engineering**

— Concurrency and Parallelism / 2019-20 —

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# Agenda

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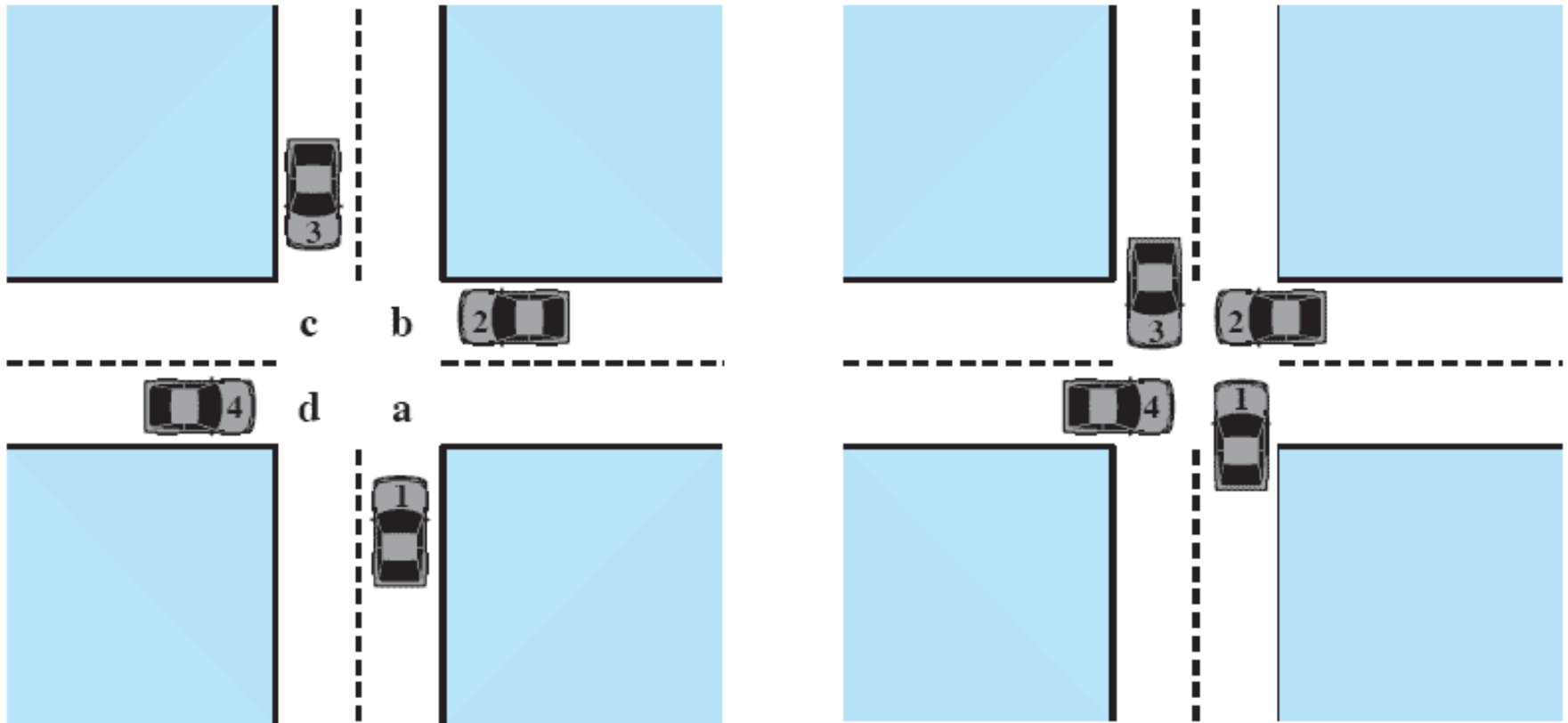
- Concurrency Anomalies
- Assigning Semantics to Concurrent Programs
- Concurrency Errors
  - Detection of data races
  - Detection of high-level data races and stale value errors
  - Detection of deadlocks

# Deadlocks

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# Deadlock

Permanent blocking of a set of processes that either compete for system resources or communicate with each other.



(a) Deadlock possible

(b) Deadlock



# System Model

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- Finite number of resources
- Resources are organized into classes
  - Each class only contain identical resource instances
- Processes compete for accessing resources
- If a process request an instance of a resource class, *any* instance of that class must satisfy the process

# Protocol to Use a Resource

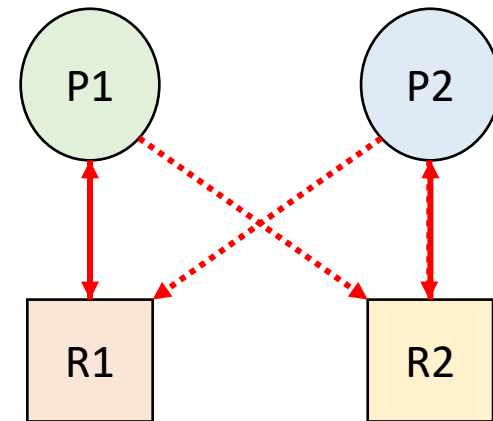
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- **Request** — The process either gets an instance of the resource immediately; or waits until one is available (and gets it)
- **Use** — The process can operate on its resource instance
- **Release** — The process releases its resource instance
- Examples: `malloc()` & `free()` — `open()` & `close()`

# Deadlock

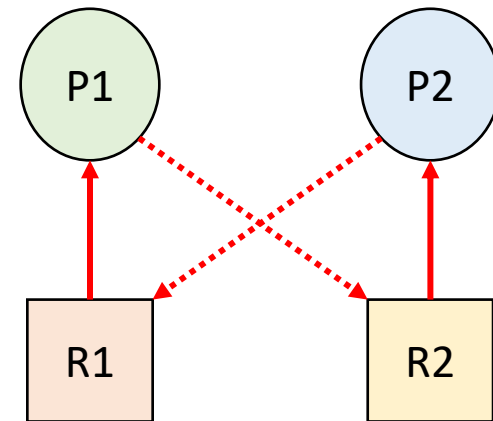
A set of two or more processes are deadlocked if:

1. They are blocked (i.e., in the waiting state)
2. Each is holding a resource
3. Each is waiting to acquire a resource held by another process in the set



# Deadlock

- Deadlock depends on the dynamics of the execution
- Is difficult to identify and test for deadlocks, which may occur only under certain circumstances



# Conditions Necessary for Deadlock

- **mutual exclusion:** only one process can use a resource at a time
- **hold and wait:** a process holding at least one resource is waiting to acquire additional resources which are currently held by other processes
- **no preemption:** a resource can only be released voluntarily by the process holding it
- **circular wait:** a cycle of process requests exists (i.e.,  $P_0 \rightarrow P_1 \rightarrow P_2 \rightarrow \dots \rightarrow P_{n-1} \rightarrow P_0$ ).

# Example

## Thread 1

```
void *do_work_one(void *param) {  
    pthread_mutex_lock(&m1);  
    pthread_mutex_lock(&m2);  
    /**  
     * Do some work  
     */  
    pthread_mutex_unlock(&m2);  
    pthread_mutex_unlock(&m1);  
    pthread_exit(0);  
}
```

## Thread 2

```
void *do_work_two(void *param) {  
    pthread_mutex_lock(&m2);  
    pthread_mutex_lock(&m1);  
    /**  
     * Do some work  
     */  
    pthread_mutex_unlock(&m1);  
    pthread_mutex_unlock(&m2);  
    pthread_exit(0);  
}
```

# Example

## Thread 1

```
void *do_work_one(void *param) {  
    pthread_mutex_lock(&m1);  
    pthread_mutex_lock(&m2);  
    /**  
     * Do some work  
     */  
    pthread_mutex_unlock(&m2);  
    pthread_mutex_unlock(&m1);  
    pthread_exit(0);  
}
```

*Will deadlock  
happen?*

## Thread 2

```
void *do_work_two(void *param) {  
    pthread_mutex_lock(&m2);  
    pthread_mutex_lock(&m1);  
    /**  
     * Do some work  
     */  
    pthread_mutex_unlock(&m1);  
    pthread_mutex_unlock(&m2);  
    pthread_exit(0);  
}
```

# Example

*Only if executed in order:*

- 1, 3, 2, 4; or
- 1, 3, 4, 2; or
- 3, 1, 2, 4; or
- 3, 1, 4, 2

## Thread 1

```
void *do_work_one(void *param) {  
  1 pthread_mutex_lock(&m1);  
  2 pthread_mutex_lock(&m2);  
  /**  
   * Do some work  
   */  
  pthread_mutex_unlock(&m2);  
  pthread_mutex_unlock(&m1);  
  pthread_exit(0);  
}
```

## Thread 2

```
void *do_work_two(void *param) {  
  3 pthread_mutex_lock(&m2);  
  4 pthread_mutex_lock(&m1);  
  /**  
   * Do some work  
   */  
  pthread_mutex_unlock(&m1);  
  pthread_mutex_unlock(&m2);  
  pthread_exit(0);  
}
```

*These orderings are ok:*

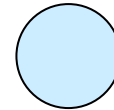
- 1, 2, 3, 4; and
- 3, 4, 1, 2

# Resource Allocation Graph

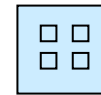
- A set of vertices **V** and a set of edges **E**
- **V** is partitioned into two types:
  - $P = \{P_1, P_2, \dots, P_n\}$ , the set of all the processes in the system
  - $R = \{R_1, R_2, \dots, R_m\}$ , the set of all resource types in the system
- **E** is partitioned into two types:
  - Request edge – directed edge  $P_i \rightarrow R_j$
  - Assignment edge – directed edge  $R_j \rightarrow P_i$

# Resource Allocation Graph

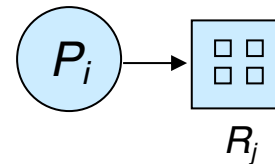
- Process



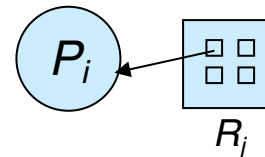
- Resource Type with 4 instances



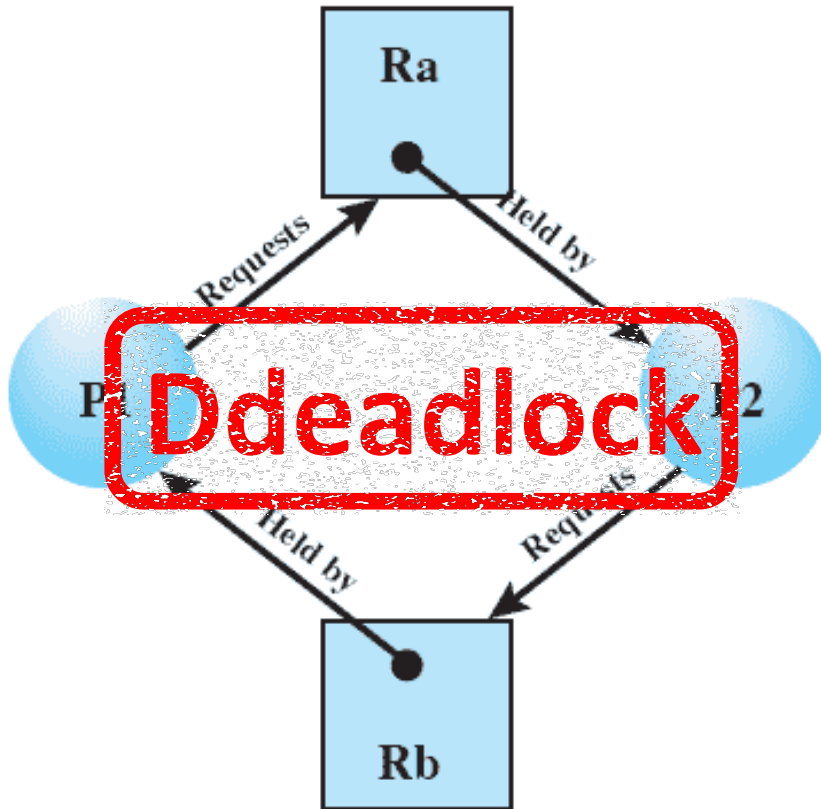
- $P_i$  requests instance of  $R_j$



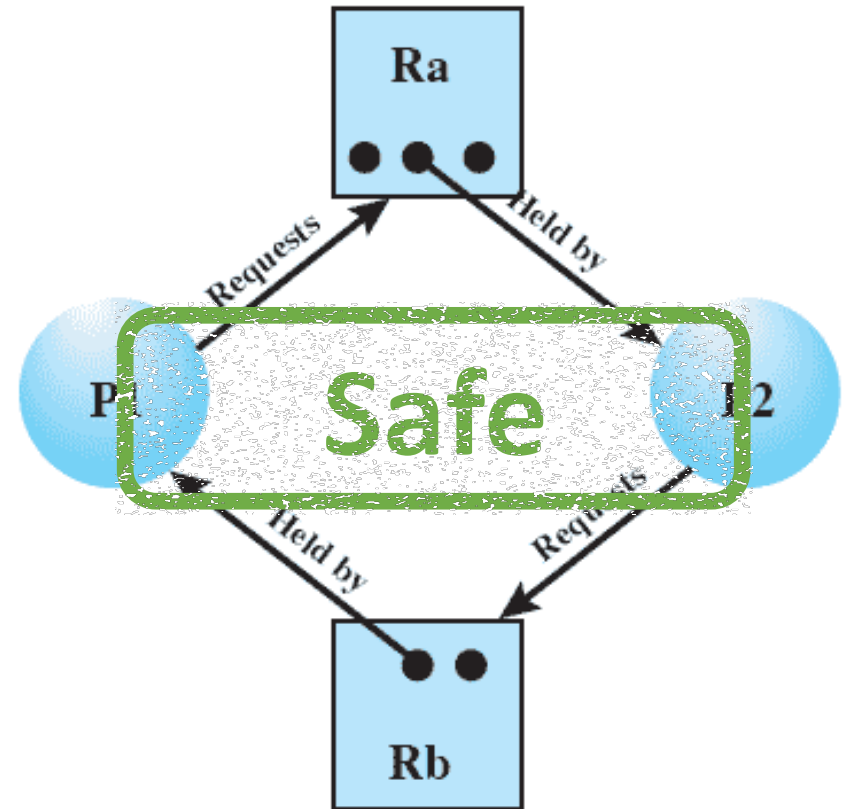
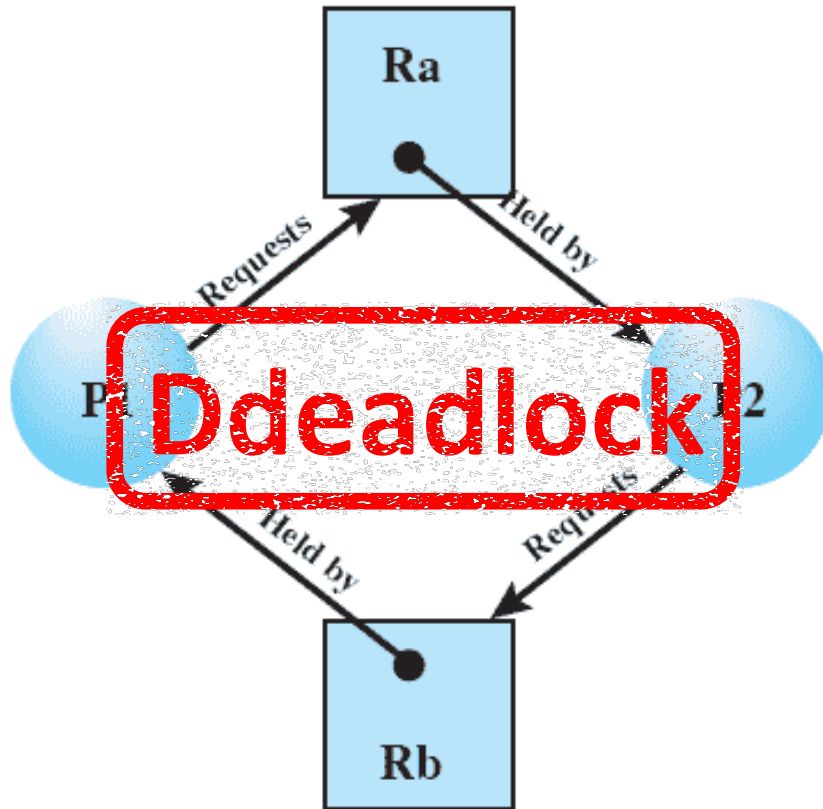
- $P_i$  is holding an instance of  $R_j$



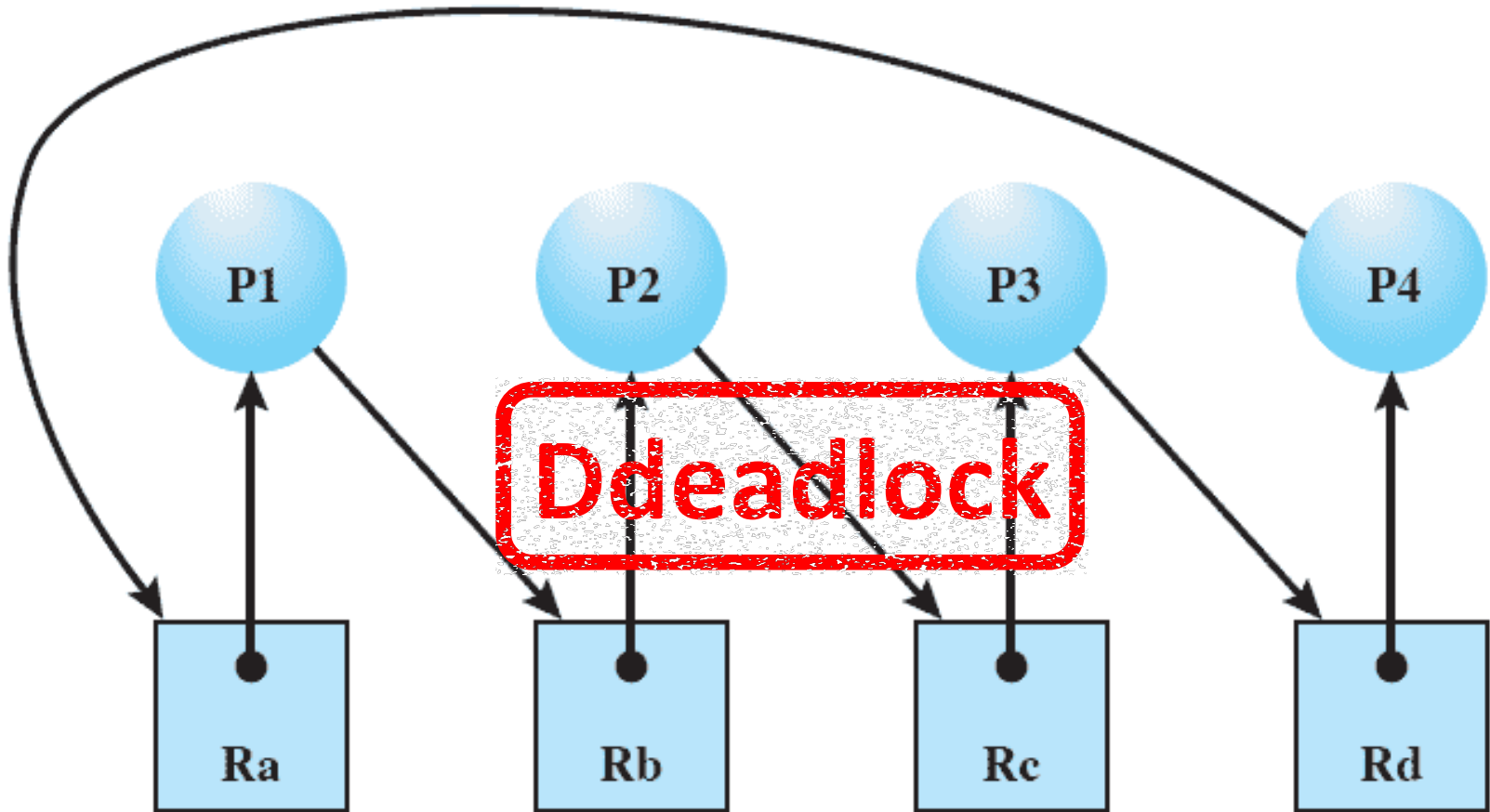
# Example of Resource Allocation Graphs



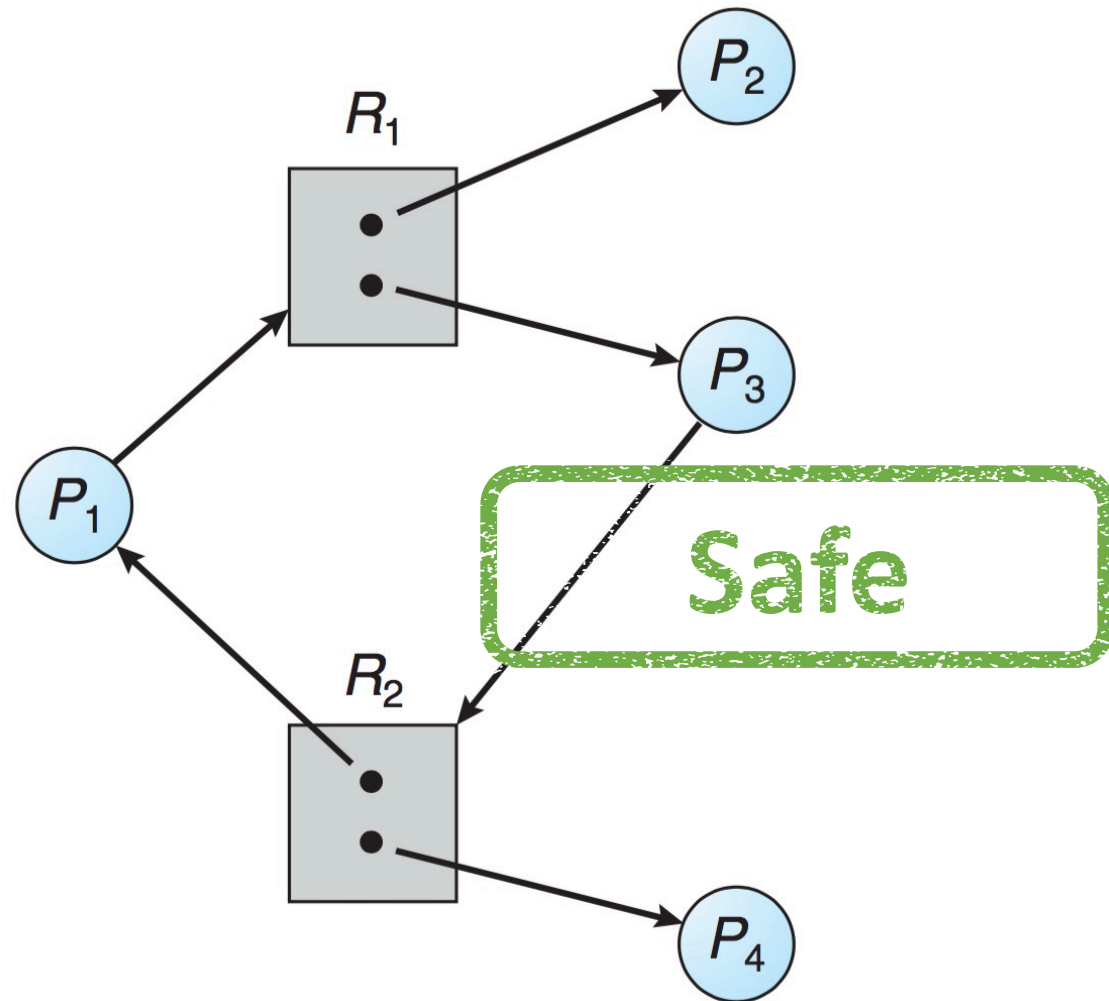
# Example of Resource Allocation Graphs



# Example of Resource Allocation Graphs



# Example of Resource Allocation Graphs



# Basic Facts

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- If graph contains no cycles  $\Rightarrow$  no deadlock
- If graph contains a cycle  $\Rightarrow$ 
  - if only one instance per resource type, then deadlock
  - if several instances per resource type, possibility of deadlock

# How to Deal with Deadlocks?

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- Deadlock prevention
- Deadlock avoidance



*The system never enters  
a deadlock state*

# How to Deal with Deadlocks?

- Deadlock prevention
  - Deadlock avoidance
  - Deadlock detection and recovery
  - Ignore the issue! ;)
- The system never enters a deadlock state*
- The system may enter a deadlock state*

# Deadlocks

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## Deadlock prevention

# Deadlock Prevention

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- Provides a set of methods to ensure that at least one of the necessary conditions cannot hold
- These methods prevent deadlocks by constraining how requests for resources can be made

# Conditions Necessary for Deadlock

- **mutual exclusion:** only one process can use a resource at a time
- **hold and wait:** a process holding at least one resource is waiting to acquire additional resources which are currently held by other processes
- **no preemption:** a resource can only be released voluntarily by the process holding it
- **circular wait:** a cycle of process requests exists (i.e.,  $P_0 \rightarrow P_1 \rightarrow P_2 \rightarrow \dots \rightarrow P_{n-1} \rightarrow P_0$ ).

# Deadlock Prevention

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- Restrict the way requests can be made...
- **Mutual Exclusion**
  - not required for sharable resources (e.g., read-only files); must hold for non-sharable resources
- **Hold and Wait**
  - must guarantee that whenever a process requests a resource, it does not hold any other resources
  - require process to request and allocate all its resources before it begins execution
  - low resource utilization; starvation possible

# Deadlock Prevention

- Restrict the way requests can be made...
- **No Preemption**
  - if a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are released
  - preempted resources are added to the list of resources for which the process is waiting
  - process will be restarted only when it can regain its old resources, as well as the new ones that it is requesting
- **Circular Wait**
  - impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration

# Example of Deadlock with Lock Ordering

```
void transaction(Account from, Account to,  
                double amount) {
```

```
    from.lock();
```

```
    to.lock();
```

```
    from.withdraw(amount);
```

```
    to.deposit(amount);
```

```
    to.unlock();
```

```
    from.unlock();
```

```
}
```

## Thread 1

```
transaction (A, B, 25);
```

## Thread 2

```
transaction (B, A, 50);
```

# Deadlocks

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## Deadlock avoidance

# Deadlock Avoidance

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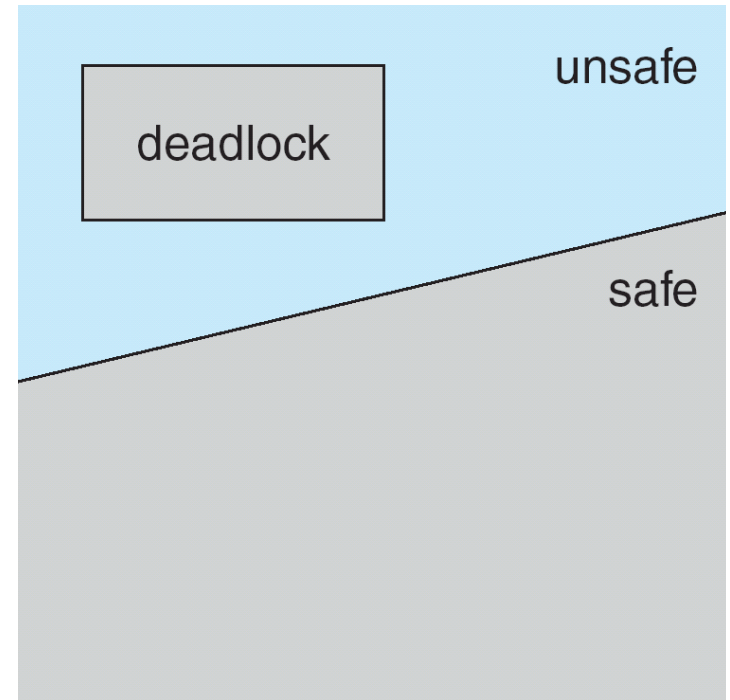
- Requires that the system has some additional *a priori* information available
  - Requires that each process declare the maximum number of resources of each type that it may need
  - The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition
  - Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes

# Safe State

- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state
- **System is in safe state** if there exists a sequence  $\langle P_1, P_2, \dots, P_n \rangle$  of ALL the processes in the system such that for each  $P_i$ , the resources that  $P_i$  can still request can be satisfied by currently available resources + resources held by all the  $P_j$ , with  $j < i$
- That is:
  - If  $P_i$  resource needs are not immediately available, then  $P_i$  can wait until all  $P_j$  have finished
  - When  $P_j$  is finished,  $P_i$  can obtain needed resources, execute, return allocated resources, and terminate
  - When  $P_i$  terminates,  $P_{i+1}$  can obtain its needed resources, and so on

# Deadlock Avoidance

- If a system is in safe state  $\Rightarrow$  no deadlocks
- If a system is in unsafe state  $\Rightarrow$  possibility of deadlock
- Avoidance  $\Rightarrow$  ensure that a system will never enter an unsafe state



# Avoidance Algorithms

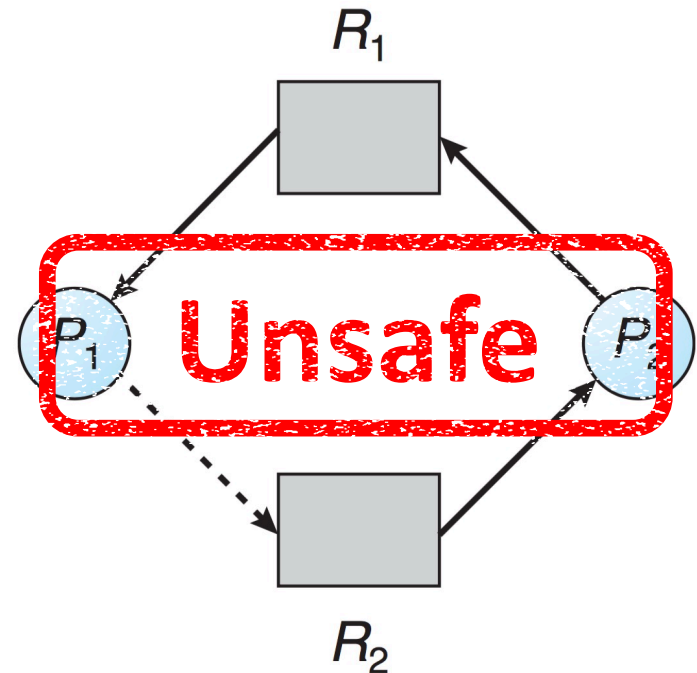
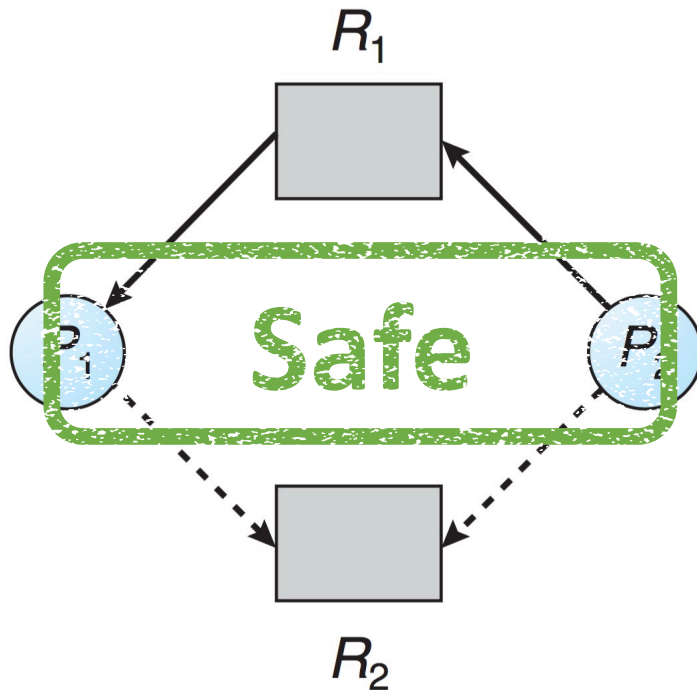
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- Single instance of a resource type  
Use a resource-allocation graph
- Multiple instances of a resource type  
Use the banker's algorithm

# Resource-Allocation Graph Scheme

- Claim edge  $P_i \dashrightarrow R_j$  indicated that process  $P_i$  may request resource  $R_j$ ; represented by a dashed line
- Claim edge converts to request edge when a process requests a resource
- Request edge converted to an assignment edge when the resource is allocated to the process
- When a resource is released by a process, assignment edge reconverts to a claim edge
- Resources must be claimed a priori in the system

# Resource-Allocation Graph



# Banker's Algorithm

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- Resources may have multiple instances
- Each process must a priori claim maximum use
- When a process requests a resource it may have to wait
- When a process gets all its resources it must return them in a finite amount of time

# Banker's Algorithm

<https://www.youtube.com/watch?v=w0LwGqffUkg>

Initial		
A	B	C
10	5	7

Available		
A	B	C
3	3	2

Allocation			
	A	B	C
P <sub>0</sub>	0	1	0
P <sub>1</sub>	2	0	0
P <sub>2</sub>	3	0	2
P <sub>3</sub>	2	1	1
P <sub>4</sub>	0	0	2

7	2	5
---	---	---

	Max		
	A	B	C
P <sub>0</sub>	7	5	3
P <sub>1</sub>	3	2	2
P <sub>2</sub>	9	0	2
P <sub>3</sub>	2	2	2
P <sub>4</sub>	4	3	3

	A	B	C
$P_0$	7	4	3
$P_1$	1	2	2
$P_2$	6	0	0
$P_3$	0	1	1
$P_4$	4	3	1

	Available		
$P_0$ — finish[0] = F			
$P_1$ — finish[1] = T	<b>5</b>	<b>3</b>	<b>2</b>
$P_2$ — finish[2] = F			
$P_3$ — finish[3] = T	<b>7</b>	<b>4</b>	<b>3</b>
$P_4$ — finish[4] = T	<b>7</b>	<b>4</b>	<b>5</b>

	Available		
$P_0$ — finish[0] = T	7	5	5
$P_2$ — finish[2] = T	10	5	7

**$\langle P_1, P_3, P_4, P_0, P_2 \rangle$**

# Deadlocks

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## Deadlock detection

# Deadlock Detection

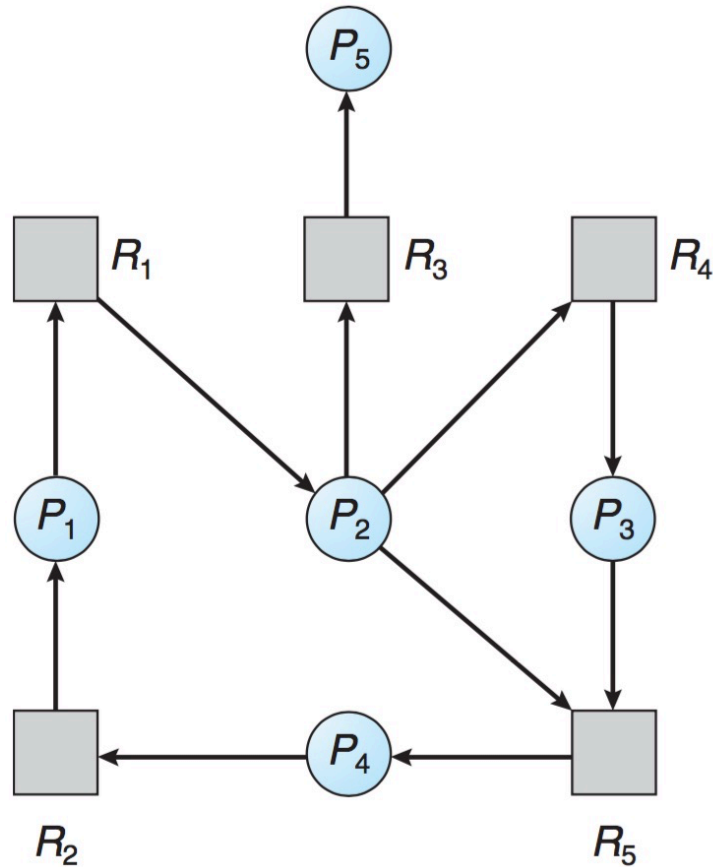
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- If neither avoidance nor prevention is implemented, deadlocks can (and will) occur.
- Coping with this requires:
  - **Detection**: finding out if deadlock has occurred
    - Keep track of resource allocation (who has what)
    - Keep track of pending requests (who is waiting for what)
  - **Recovery**: resolve the deadlock

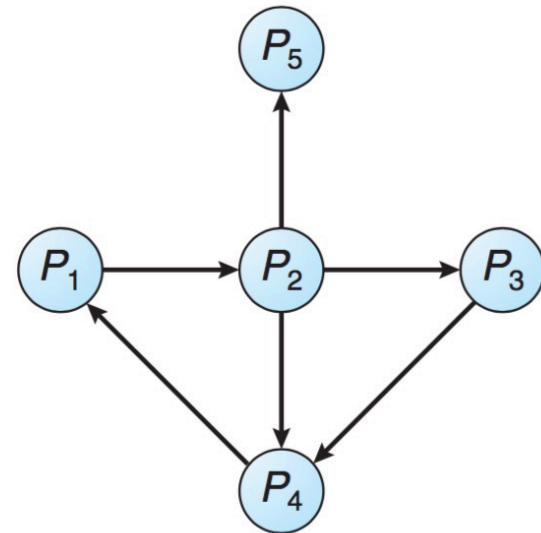
# Single Instance of Each Resource Type

- Maintain a *wait-for* graph
  - Nodes are processes
  - $P_i \rightarrow P_j$  if  $P_i$  is waiting for a resource held by  $P_j$
- Periodically invoke an algorithm that searches for a cycle in the graph
  - If there is a cycle, there exists a deadlock
- An algorithm to detect a cycle in a graph requires an order of  $n^2$  operations, where  $n$  is the number of vertices in the graph

# Resource-Allocation Graph and Wait-for Graph



Resource-Allocation Graph



Corresponding wait-for graph

# Several Instances of a Resource Type

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- Yes! It is possible!
- Algorithm inspired in the Banker's algorithm

# Strategies Once Deadlock Detected

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- Abort all deadlocked processes
- Resource preemption
- Roll back each deadlocked process to some previously defined checkpoint, and restart all process
  - Original deadlock may occur

# Recovery from Deadlock: Process Termination

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- Abort all deadlocked processes
- Abort one process at a time until the deadlock cycle is eliminated
- In which order should we choose to abort?
  - Priority of the process?
  - How long process has computed, and how much longer to completion?
  - Resources the process has used?
  - Resources process needs to complete?
  - How many processes will need to be terminated?
  - Is process interactive or batch?

# Recovery from Deadlock: Resource Preemption

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- **Selecting a victim** – minimize cost
- **Rollback** – return to some safe state, restart process for that state
- **Starvation** – same process may always be picked as victim, include number of rollback in cost factor

# Roll Back

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- Roll back all the processes
  - Possibly to a situation where no locks are being held
- Pray for the deadlock to not happen again

# Acknowledgments

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- Some parts of this presentation was based in publicly available slides and PDFs
  - [www.cs.cornell.edu/courses/cs4410/2011su/slides/lecture10.pdf](http://www.cs.cornell.edu/courses/cs4410/2011su/slides/lecture10.pdf)
  - [www.microsoft.com/en-us/research/people/madanm/](http://www.microsoft.com/en-us/research/people/madanm/)
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# The END

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