

#### Parallel Performance

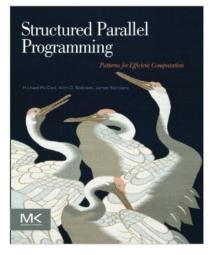
Concurrency and Parallelism — 2019-20 Master in Computer Science (Mestrado Integrado em Eng. Informática)

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Source: Parallel Computing, CIS 410/510, Department of Computer and Information Science

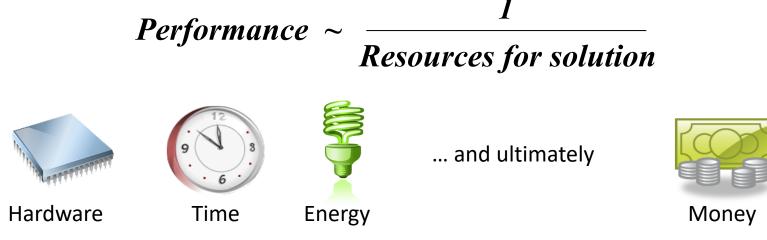
# Outline

- Performance scalability
  - Analytical performance measures
  - Amdahl' s law
  - Gustafson-Barsis' law
  - Work-span and Brent's lemma
  - Bibliography:
    - Chapter 2 of book McCool M., Arch M., Reinders J.; Structured Parallel Programming: Patterns for Efficient Computation; Morgan Kaufmann (2012); ISBN: 978-0-12-415993-8



# What is Performance?

- In computing, performance is defined by 2 factors
  - Computational requirements (what needs to be done?) Efficacy
  - Computing resources (how much will it cost?) Efficiency
- Computational problems translate to requirements
- Computing resources interplay and tradeoff



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# What is Parallel Performance?

- We are concerned with performance issues when using a parallel computing environment
  - Performance with respect to parallel computation
- Performance is the raison d'être for parallelism
  - Parallel performance versus sequential performance
  - If the "performance" is not better, parallelism is not necessary
- Parallel processing includes techniques and technologies necessary to compute in parallel
  - Hardware, networks, operating systems, parallel libraries, languages, compilers, algorithms, tools, ...
- Parallelism must deliver performance
  - How? How well?

# Performance Expectation (Loss)

- If each processor is rated at "f" MFLOPS and there are "p" processors, should we see " $f \times p$ " MFLOPS performance?
  - If it takes 100 seconds on 1 processor, shouldn't it take 10 seconds on 10 processors?
- Several causes affect performance
  - Each must be understood separately
  - But they interact with each other in complex ways
    - Solution to one problem may create another
    - One problem may mask another
- Scaling (system, problem size) can change conditions
- Need to understand performance space

## Embarrassingly Parallel Computations

- An embarrassingly parallel computation is one that can be obviously divided into completely independent parts that can be executed simultaneously
  - In a truly embarrassingly parallel computation there is no interaction between separate processes
  - In a nearly embarrassingly parallel computation results must be distributed and collected/combined in some way
- Embarrassingly parallel computations have potential to achieve maximal speedup on parallel platforms
  - If it takes T time sequentially, there is the potential to achieve T/P time running in parallel with P processors
  - Why is this not always the case?

# Scalability

- Can the program scale up to use many processors? – What does that mean?
- How do we evaluate scalability?
- How do we evaluate scalability goodness?
- Comparative evaluation
  - If double the number of processors, what to expect?
  - Is scalability linear?
- Use parallel efficiency measure – Is efficiency retained as problem size increases?
- Apply performance metrics

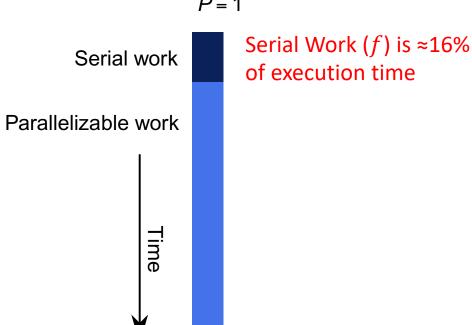
# Performance and Scalability

- Evaluation
  - Sequential runtime  $(T_{seq} \text{ or } T_1)$  is a function of
    - problem size and architecture
  - Parallel runtime  $(T_{par})$  is a function of
    - problem size and parallel architecture
    - # processors used in the execution
  - Parallel performance is affected by
    - algorithm + architecture
- Scalability
  - Ability of parallel algorithm to achieve performance gains proportional to the number of processors and the size of the problem

#### Performance Metrics and Formulas

- $T_1$  is the execution time on a single processor
- $T_p$  is the execution time on a "p" processor system
- $S_p$  is the speedup  $S(p) = \frac{T_1}{T_p}$
- $E_p$  is the efficiency  $E(p) = \frac{S_p}{p}$
- $C_p$  is the cost  $Cost(p) = p \times T_p$
- A parallel algorithm is cost-optimal if
   Σ Parallel time = sequential time (E<sub>p</sub> = 100%, C<sub>p</sub> = T<sub>1</sub>)

- Interested in solving the problem faster
- Reduce execution time



P = 1

- Interested in solving the problem faster
- Reduce execution time

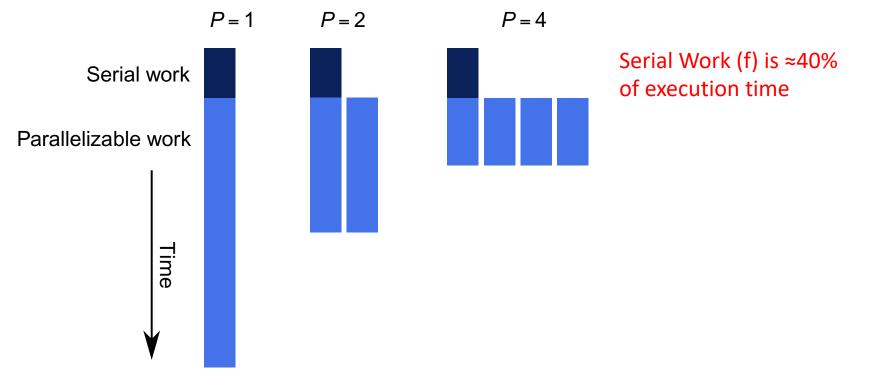
P = 1

Serial work
Parallelizable work

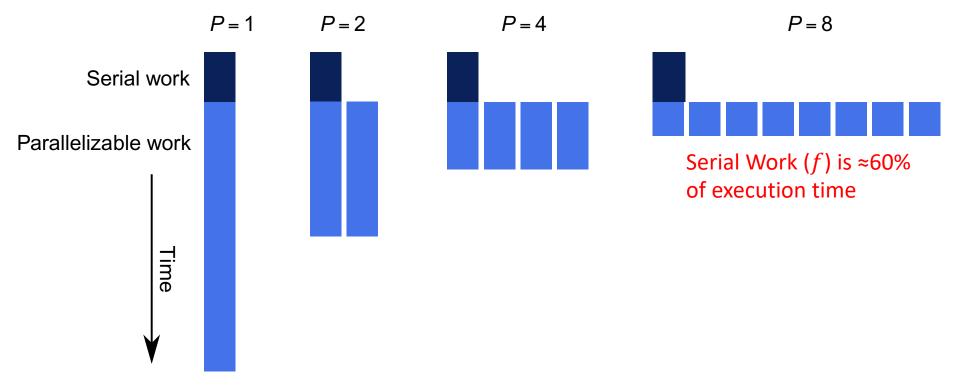
*P* = 2

Serial Work (f) is  $\approx 25\%$  of execution time

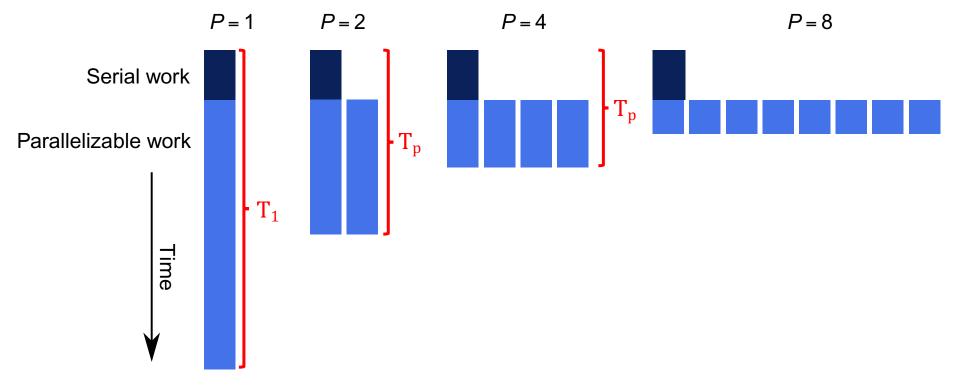
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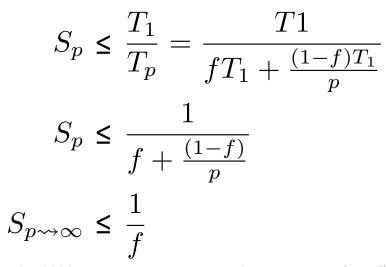
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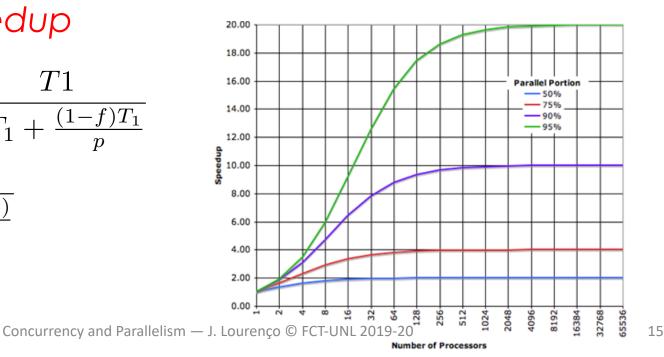


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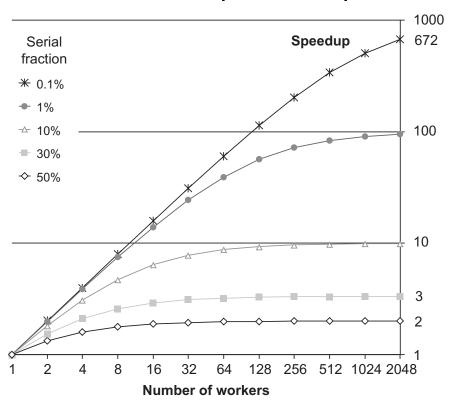


- Let f be the fraction of a program that is sequential -1-f is the fraction that can be parallelized
- Let  $T_1$  be the execution time on 1 processor
- Let  $T_p$  be the execution time on p processors
- $S_p$  is the speedup

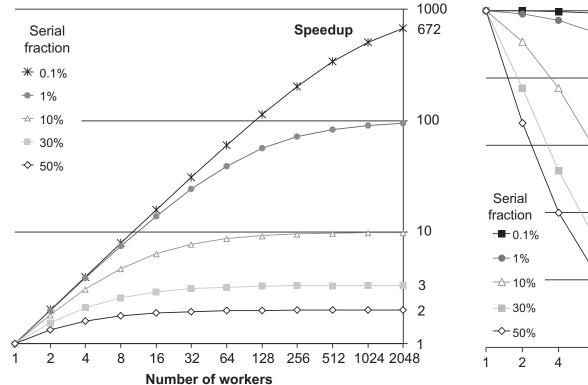




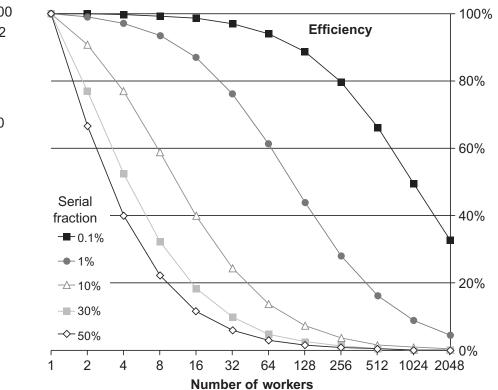
 Amdhal's Law: Maximal Speedup



 Amdhal's Law: Maximal Speedup



 Amdahl's Law: Efficiency



# Amdahl's Law (Example)

- If 90% of the computation can be parallelized, what is the max. speedup achievable using 8 processors?
- Solution:

$$f = 10\% = 0.1$$
$$S(8) \le \frac{1}{0.1 + \frac{1 - 0.1}{8}} \approx 4.7$$

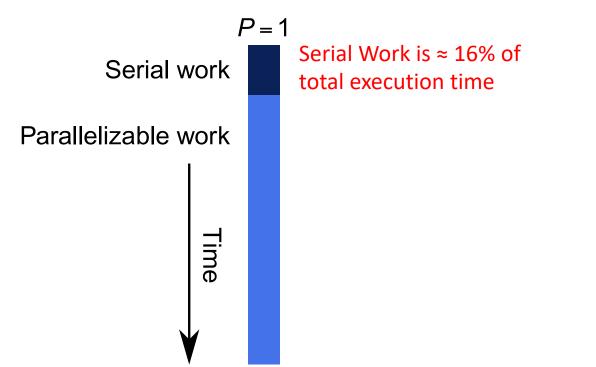
# Amdahl's Law and Scalability

- Scalability
  - Ability of parallel algorithm to achieve performance gains proportional to the number of processors and the size of the problem
- When does Amdahl's Law apply?
  - When the problem size is fixed
  - Strong scaling ( $p \rightarrow \infty$ ,  $S_p = S_{\infty} \rightarrow 1 / f$ )
  - Speedup bound is determined by the degree of sequential execution time in the computation, not # processors!!!
  - Uhh, this is not good ... Why?
  - Perfect efficiency is hard to achieve
- See original paper by Amdahl at
  - http://inst.eecs.berkeley.edu/~n252/sp07/Papers/Amdahl.pdf

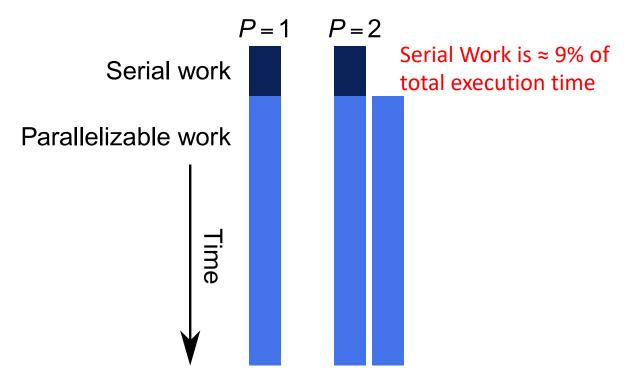
...speedup should be measured by scaling the problem to the number of processors, not by fixing the problem size.

— John Gustafson

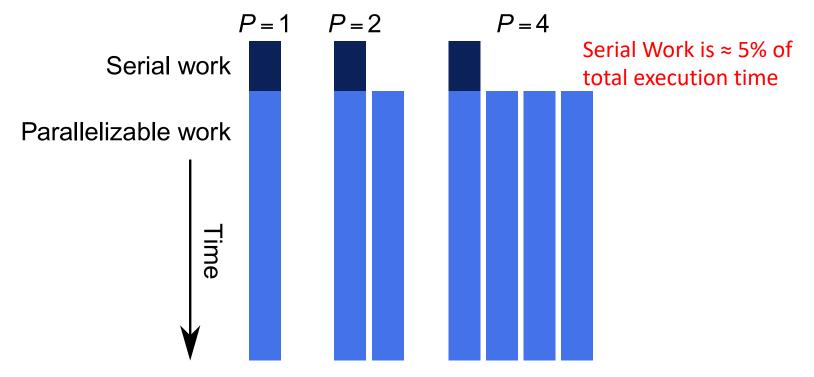
- Often interested in larger problems when scaling
  - How big of a problem can be run (HPC Linpack)
  - Constrain problem size by parallel time



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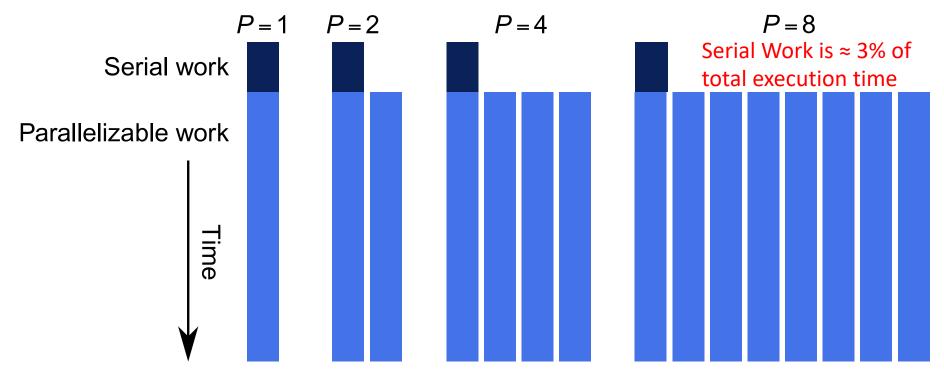


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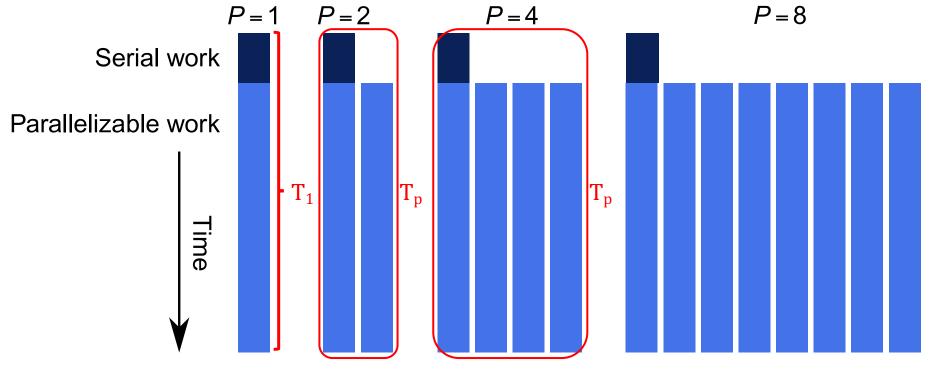


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- Execution time of a parallel program:  $T_1 = a + b$ 
  - $-a \Rightarrow$  part not parallelizable
  - $-b \Rightarrow$  part parallelizable
- Because we are scaling the problem (data being processed), with "P" processors we have:  $T_P = a + P \cdot b$
- The wall clock execution time is always the same, so scaled speedup is calculated on the volume of data processed (which is proportional to the total/accumulated execution time):  $S_p \leq T_p / T_1 = (a + P \cdot b) / (a + b)$

- Scaled speedup  $S_p \leq T_p / T_1 = (a + P \cdot b) / (a + b)$
- Let  $\alpha = a / (a + b)$  be the sequential fraction of the parallel execution time
- Then the scaled speedup is

$$S_p \leq \alpha + P \cdot (1 - \alpha) = P - \alpha \cdot (P - 1)$$

• If  $\alpha \rightarrow 0$  then  $S_p \rightarrow P$ 

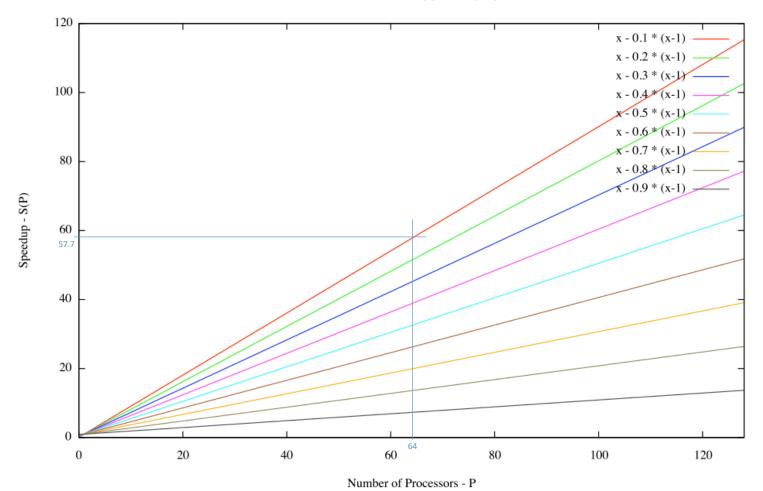
# Gustafson-Barsis' Law (Example)

- An application executing on 64 processors spends 5% of the total time on non-parallelizable computations. What is the scaled speedup?
- Solution:

$$S(64) \le P - \alpha \cdot (P - 1)$$
  
 $\le 64 - 0.05 (64 - 1)$   
 $\le 60.85$ 

#### Gustafson-Barsis' Law

Gustafson's Law:  $S(P) = P-a^*(P-1)$ 

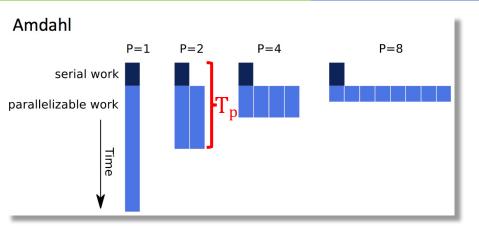


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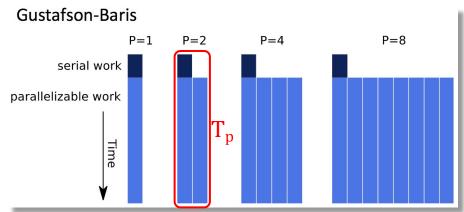
# Gustafson-Barsis' Law and Scalability

- Scalability
  - Ability of parallel algorithm to achieve performance gains proportional to the number of processors and the size of the problem
- When does Gustafson's Law apply?
  - When the problem size can increase when the number of processors increases
  - Speedup function includes the number of processors!!!
  - Can maintain or increase parallel efficiency as the problem scales

# Amdahl versus Gustafson-Baris



- Time: wall clock time
- Sequential part tends to dominate computation
- Upper-bound on scalability



- Time: CPU time
- Sequential part tends to become irrelevant
- No upper-bound on scalability

## The END