

Análise Matemática II E

Exame de Ética 2

14/07/2020

Nota: Esta é apenas uma sugestão de resolução de entre muitas outras possibilidades.

①

a) $y(t) \rightarrow$ quantidade (em gramas) do elemento químico no organismo do paciente no instante t

$$\begin{cases} y(0) = 2g \\ y' = ky \end{cases}$$

b) $y' = ky \Leftrightarrow y' - ky = 0$

Como esta uma EDO linear, começamos por determinar um factor integrante para a mesma

$$\mu(t) = e^{\int -k dt} = e^{-kt}$$

Assim vem

$$e^{-kt} y' - k e^{-kt} y = 0 \Leftrightarrow$$

$$\Leftrightarrow \frac{d}{dt} (e^{-kt} y) = 0 \Leftrightarrow e^{-kt} y = e, e \in \mathbb{R}$$

$$\Leftrightarrow y = e e^{kt}, e \in \mathbb{R}$$

(2)

Como $y(0) = 27$ temos

$$27 = e \cdot 2^0 \Rightarrow e = 27$$

$$\therefore y = 27 \cdot 2^{kt}$$

$$c) \quad y(1) = 26.9 \Rightarrow 26.9 = 27 \cdot 2^k \Rightarrow$$

$$\Rightarrow \frac{26.9}{27} = 2^k \Rightarrow$$

$$\Rightarrow k = \log\left(\frac{26.9}{27}\right)$$

$$\therefore y = 27 \cdot 2^{\log\left(\frac{26.9}{27}\right)t}$$

$$y(t) = 13.5 \Rightarrow 13.5 = 27 \cdot 2^{\log\left(\frac{26.9}{27}\right)t}$$

$$\Rightarrow \frac{13.5}{27} = 2^{\log\left(\frac{26.9}{27}\right)t}$$

$$\Rightarrow \log\left(\frac{13.5}{27}\right) = \log\left(\frac{26.9}{27}\right)t$$

$$\Rightarrow t = \frac{\log\left(\frac{13.5}{27}\right)}{\log\left(\frac{26.9}{27}\right)} \text{ horas}$$

$$(2) \quad x^3 + x^3 y^4 = y y' e^{-x^2} \quad (\Rightarrow)$$

$$(\Rightarrow) \quad x^3 (1 + y^4) = y y' e^{-x^2} \quad (\Rightarrow)$$

$$(\Rightarrow) \quad x^3 e^{x^2} = \frac{y}{1+y^4} y' \quad (\Rightarrow)$$

$$(\Rightarrow) \quad \int x^3 e^{x^2} dx = \int \frac{y}{1+y^4} y' dx \quad (\Rightarrow)$$

$$(\Rightarrow) \quad \int x^3 e^{x^2} dx = \int \frac{y}{1+y^4} dy$$

Determinemos $\int x^3 e^{x^2} dx$ utilizando integração por partes

$$\begin{aligned} \int x^3 e^{x^2} dx &= \int x^2 x e^{x^2} dx = x^2 \frac{e^{x^2}}{2} - \int x e^{x^2} dx = \\ &= x^2 \frac{e^{x^2}}{2} - \frac{e^{x^2}}{2} + c, c \in \mathbb{R} \end{aligned}$$

Adicionamos

$$x^2 \frac{e^{x^2}}{2} - \frac{e^{x^2}}{2} + c_1 = \frac{1}{2} \arctg(y^2) + c_2, c_1, c_2 \in \mathbb{R} \quad (\Rightarrow)$$

$$(\Rightarrow) \quad \arctg(y^2) = x^2 e^{x^2} - e^{x^2} + c_3, c_3 \in \mathbb{R} \quad (\Rightarrow)$$

$$(\Rightarrow) \quad y^2 = \operatorname{tg}(x^2 e^{x^2} - e^{x^2} + c_3), c_3 \in \mathbb{R} \quad (\Rightarrow)$$

$$(\Rightarrow) \quad y = \pm \sqrt{\operatorname{tg}(x^2 e^{x^2} - e^{x^2} + c_3)}, c_3 \in \mathbb{R}$$

(3)

③
a) É possível hadlongar f ha continuidade a

$(0, -2)$ se $\lim_{(x,y) \rightarrow (0,-2)} f(x,y)$ existe.

$$\lim_{(x,y) \rightarrow (0,-2)} f(x,y) = \lim_{(x,y) \rightarrow (0,-2)} x(y+2) \log(x^2 + (y+2)^2) + x$$

$$= \lim_{\rho \rightarrow 0} \rho^2 \cos \theta \sin \theta \log(\rho^2) + \rho \cos \theta$$

$$\begin{cases} x = \rho \cos \theta & \rho > 0 \\ y = -2 + \rho \sin \theta & \theta \in [0, 2\pi[\end{cases}$$

Como

$$\lim_{\rho \rightarrow 0} \rho^2 \log(\rho^2) = \lim_{\rho \rightarrow 0} \frac{-\log\left(\frac{1}{\rho^2}\right)}{\frac{1}{\rho^2}} = -0 = 0$$

$$\lim_{\rho \rightarrow 0} \rho = 0$$

e $\cos \theta \sin \theta$ e $\cos \theta$ são limitadas entre -1 e 1 ,

podemos concluir que

$$\lim_{\rho \rightarrow 0} \rho^2 \log(\rho^2) \cos \theta \sin \theta + \rho \cos \theta = 0 + 0 = 0$$

Assim, é possível hadlongar f ha continuidade a $(0, -2)$ sendo a função hadlongamento definida

h01

(5)

$$\bar{f}(x, y) = \begin{cases} x(y+2) \log(x^2 + (y+2)^2) + x, & \text{se } (x, y) \neq (0, -2) \\ 0, & \text{se } (x, y) = (0, -2) \end{cases}$$

6)

$$\begin{aligned} \frac{d\bar{f}}{dx}(0, -2) &= \lim_{h \rightarrow 0} \frac{\bar{f}(h, -2) - \bar{f}(0, -2)}{h} = \\ &= \lim_{h \rightarrow 0} \frac{h \times 0 \times \log(h^2) + h - 0}{h} = \\ &= \lim_{h \rightarrow 0} \frac{h}{h} = \lim_{h \rightarrow 0} 1 = 1 \end{aligned}$$

$$\begin{aligned} \frac{d\bar{f}}{dy}(0, -2) &= \lim_{h \rightarrow 0} \frac{\bar{f}(0, -2+h) - \bar{f}(0, -2)}{h} = \\ &= \lim_{h \rightarrow 0} \frac{0 \times h \times \log(h^2) + 0}{h} = \lim_{h \rightarrow 0} 0 = 0 \end{aligned}$$

Se $\bar{f}$ for diferenciável em $(0, -2)$ então

$$d\bar{f}(0, -2)(h_1, h_2) = h_1$$

(6)

$\bar{f}$ é diferenciável em $(0, -2)$ ssa

$$\bar{f}(0+h_1, -2+h_2) = \bar{f}(0, -2) + d\bar{f}(0, -2)(h_1, h_2) + \\ + \| (h_1, h_2) \| \epsilon(h_1, h_2), \text{ com}$$

$$\lim_{(h_1, h_2) \rightarrow (0, 0)} \epsilon(h_1, h_2) = 0$$

$$(h_1, h_2) \rightarrow (0, 0)$$

$$\begin{aligned} \lim_{(h_1, h_2) \rightarrow (0, 0)} \epsilon(h_1, h_2) &= \lim_{(h_1, h_2) \rightarrow (0, 0)} \frac{h_1 h_2 \log(h_1^2 + h_2^2) + h_1 - h_1}{\sqrt{h_1^2 + h_2^2}} \\ &= \lim_{(h_1, h_2) \rightarrow (0, 0)} \frac{h_1 h_2 \log(h_1^2 + h_2^2)}{\sqrt{h_1^2 + h_2^2}} \end{aligned}$$

$$\begin{cases} h_1 = \rho \cos \theta \\ h_2 = \rho \sin \theta \end{cases} \quad = \lim_{\rho \rightarrow 0} \frac{\rho^2 \cos \theta \sin \theta \log(\rho^2)}{\rho} =$$

$$\begin{aligned} &\rho > 0 \\ &\theta \in [0, 2\pi[\\ &= \lim_{\rho \rightarrow 0} 2\rho \cos \theta \sin \theta \log(\rho) \end{aligned}$$

Como

$$\lim_{\rho \rightarrow 0} \rho \log(\rho) = \lim_{\rho \rightarrow 0} \frac{-\log(\frac{1}{\rho})}{\frac{1}{\rho}} = -0 = 0$$

e $\cos \theta \sin \theta$ é limitada entre -1 e 1 temos

$$\lim_{\rho \rightarrow 0} 2\rho \log(\rho) \cos \theta \sin \theta = 2 \times 0 = 0$$

Assim, $\bar{f}$ é diferenciável em $(0, -2)$

(7)

e) Sendo $\bar{f}$ diferenciável em $(0, -2)$ faz sentido usar o seu diferencial para determinar uma aproximação de primeira ordem para

$$\bar{f}(0.02, -1.999) = \bar{f}((0, -2) + (0.02, 0.001))$$

$$\approx \bar{f}(0, -2) + d\bar{f}(0, -2)(0.02, 0.001) =$$

$$= 0 + 0.02 = 0.02$$

(4a) Começamos por determinar $J_{\alpha\beta} f(x, y)$.

$$J_{\alpha\beta} f(x, y) = \begin{bmatrix} e^x \arctan(x+y) + \frac{e^x}{1+(x+y)^2} & \frac{e^x}{1+(x+y)^2} \\ \frac{2xy}{x^2+y^2} \cos(x^3y) - \log(x^2+y^2) \sin(x^3y) 3x^2y & * \end{bmatrix}$$

$$* \frac{2y}{x^2+y^2} \cos(x^3y) - \log(x^2+y^2) \sin(x^3y) x^3$$

Atendendo a que todas as derivadas parciais da função são funções contínuas em $\mathbb{R}^2 \setminus \{(0,0)\}$, pois resultam de operações algébricas e combinações de funções contínuas (exponencial, seno, cosseno, arcotangente, logaritmo e hiperbólicos), podemos concluir que $f \in \mathcal{C}^1(\mathbb{R}^2 \setminus \{(0,0)\})$ logo f é diferenciável em $\mathbb{R}^2 \setminus \{(0,0)\}$.

$$b) (g \circ f)(1,0) = g(f(1,0)) = g\left(\frac{2\pi}{4}, 0\right)$$

$g \in \mathcal{C}^1(\mathbb{R}^2)$ logo g é diferenciável em $(\frac{2\pi}{4}, 0)$

$f \in \mathcal{C}^1(\mathbb{R}^2 \setminus \{(0,0)\})$ logo f é diferenciável em $(1,0)$

A composta de funções diferenciáveis é diferenciável, pelo que $g \circ f$ é diferenciável em $(1,0)$. Sabemos

ainda que:

$$J_{(g \circ f)}(1,0) = J_{(g)}\left(\frac{2\pi}{4}, 0\right) \times J_{(f)}(1,0) =$$

$$= \begin{bmatrix} -1 & 3 \end{bmatrix} \begin{bmatrix} \frac{2\pi}{4} + \frac{2}{2} & \frac{2}{2} \\ 2 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{2\pi}{4} - \frac{2}{2} + 6 & -\frac{2}{2} \end{bmatrix} = \nabla (g \circ f)(1,0)^T$$

5

9

$$g(u, v) = f(a, r) = f(u+v, u-v)$$

$$\frac{\partial g}{\partial u} = \frac{\partial f}{\partial a} \frac{\partial a}{\partial u} + \frac{\partial f}{\partial r} \frac{\partial r}{\partial u} = \frac{\partial f}{\partial a} + \frac{\partial f}{\partial r}$$

$$\frac{\partial g}{\partial v} = \frac{\partial f}{\partial a} \frac{\partial a}{\partial v} + \frac{\partial f}{\partial r} \frac{\partial r}{\partial v} = \frac{\partial f}{\partial a} - \frac{\partial f}{\partial r}$$

$$\frac{\partial^2 g}{\partial u^2} = \frac{\partial}{\partial u} \left(\frac{\partial f}{\partial a} + \frac{\partial f}{\partial r} \right) =$$

$$= \frac{\partial^2 f}{\partial a^2} \frac{\partial a}{\partial u} + \frac{\partial^2 f}{\partial r \partial a} \frac{\partial r}{\partial u} + \frac{\partial^2 f}{\partial a \partial r} \frac{\partial a}{\partial u} + \frac{\partial^2 f}{\partial r^2} \frac{\partial r}{\partial u} =$$

$$= \frac{\partial^2 f}{\partial a^2} + \frac{\partial^2 f}{\partial r \partial a} + \frac{\partial^2 f}{\partial a \partial r} + \frac{\partial^2 f}{\partial r^2}$$

$$\frac{\partial^2 g}{\partial v^2} = \frac{\partial}{\partial v} \left(\frac{\partial f}{\partial a} - \frac{\partial f}{\partial r} \right) =$$

$$= \frac{\partial^2 f}{\partial a^2} \frac{\partial a}{\partial v} + \frac{\partial^2 f}{\partial r \partial a} \frac{\partial r}{\partial v} - \frac{\partial^2 f}{\partial a \partial r} \frac{\partial a}{\partial v} - \frac{\partial^2 f}{\partial r^2} \frac{\partial r}{\partial v} =$$

$$= \frac{\partial^2 f}{\partial a^2} - \frac{\partial^2 f}{\partial r \partial a} - \frac{\partial^2 f}{\partial a \partial r} + \frac{\partial^2 f}{\partial r^2}$$

$$\frac{\partial^2 g}{\partial u^2} + \frac{\partial^2 g}{\partial v^2} = \frac{\partial^2 f}{\partial a^2} + \cancel{\frac{\partial^2 f}{\partial r \partial a}} + \cancel{\frac{\partial^2 f}{\partial a \partial r}} + \frac{\partial^2 f}{\partial r^2} + \frac{\partial^2 f}{\partial a^2} - \cancel{\frac{\partial^2 f}{\partial r \partial a}} - \cancel{\frac{\partial^2 f}{\partial a \partial r}} + \frac{\partial^2 f}{\partial r^2}$$

$$- \cancel{\frac{\partial^2 f}{\partial a \partial r}} + \frac{\partial^2 f}{\partial r^2} = 2 \left(\frac{\partial^2 f}{\partial a^2} + \frac{\partial^2 f}{\partial r^2} \right) = 2 \times 0 = 0$$

(6)

(10)

a) Seja

$$f(x, y, z) = \operatorname{Re}m(e^{x^3 y} + 3z - 1) + \operatorname{arctg}(xz + y^2) + 1$$

$$\begin{aligned} f(0, 0, \frac{\pi}{2}) &= \operatorname{Re}m(e^0 + 3\frac{\pi}{2} - 1) + \operatorname{arctg}(0) + 1 = \\ &= \operatorname{Re}m(\cancel{1} + 3\frac{\pi}{2} - \cancel{1}) + 1 = -1 + 1 = 0 \end{aligned}$$

$$\begin{aligned} \bullet \frac{\partial f}{\partial x}(x, y, z) &= \cos(e^{x^3 y} + 3z - 1) e^{x^3 y} 3x^2 y + \\ &+ \frac{z}{1 + (xz + y^2)^2} \end{aligned}$$

$$\begin{aligned} \frac{\partial f}{\partial y}(x, y, z) &= \cos(e^{x^3 y} + 3z - 1) e^{x^3 y} x^3 + \\ &+ \frac{2y}{1 + (xz + y^2)^2} \end{aligned}$$

$$\frac{\partial f}{\partial z}(x, y, z) = 3\cos(e^{x^3 y} + 3z - 1) + \frac{x}{1 + (xz + y^2)^2}$$

Como todas as derivadas parciais são funções contínuas em $\mathbb{R}^3$, por resultarem de operações algébricas e com hofas de funções contínuas (exponencial, cosseno, polinômios), podemos

conclui que $f \in \mathcal{C}^1(\mathbb{R}^3)$ pelo que f é de classe $\mathcal{C}^1$ numa vizinhança de $(0,0,\pi/2)$ (11)

$$\bullet \frac{\partial f}{\partial x}(0,0,\pi/2) = \frac{\pi/2}{1} = \frac{\pi}{2} \neq 0$$

Logo, pelo Teorema da função implícita, existem U vizinhança de $(0,\pi/2)$ e V vizinhança de 0 e $\phi: U \rightarrow V$ tal que $\phi \in \mathcal{C}^1(U)$ e

$$\forall (\gamma,z) \in U, \forall x \in V, f(x,\gamma,z) = 0 \Leftrightarrow x = \phi(\gamma,z)$$

6) Como $\phi \in \mathcal{C}^1(U)$ e $(0,\pi/2) \in U$ sabemos que ϕ é diferenciável em $(0,\pi/2)$ logo

$$\phi'_{(3,-2)}(0,\pi/2) = \nabla \phi(0,\pi/2)^T \begin{bmatrix} 3 \\ -2 \end{bmatrix}$$

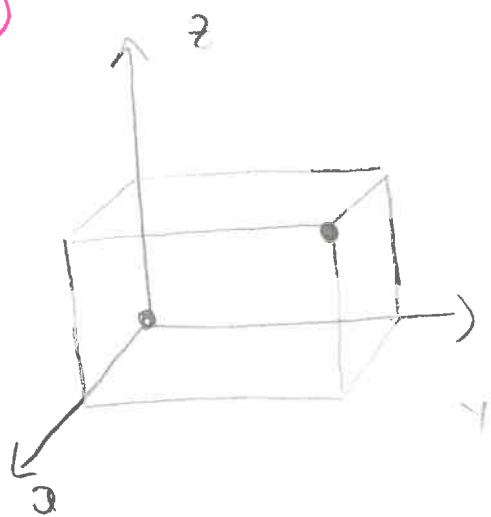
$$\frac{\partial \phi}{\partial \gamma}(0,\pi/2) = - \frac{\frac{\partial f}{\partial \gamma}(0,0,\pi/2)}{\frac{\partial f}{\partial x}(0,0,\pi/2)} = - \frac{\cos(3\pi/2) \times 0}{\pi/2} = 0$$

$$\frac{\partial \phi}{\partial z}(0,\pi/2) = - \frac{\frac{\partial f}{\partial z}(0,0,\pi/2)}{\frac{\partial f}{\partial x}(0,0,\pi/2)} = - \frac{3\cos(3\pi/2)}{\pi/2} = 0$$

$$\text{Logo } \phi'_{(3,-2)}(0,\pi/2) = [0 \ 0] \begin{bmatrix} 3 \\ -2 \end{bmatrix} = 0$$

(7)

(12)



$$\max a y z$$

$$\text{s.t. } 3x + 2y + z = 1$$

$$\mathcal{L}(x, y, z, \lambda) = a y z - \lambda (3x + 2y + z - 1), \text{ com } \lambda \in \mathbb{R}$$

$$\nabla \mathcal{L}(x, y, z, \lambda) = 0 \Leftrightarrow \begin{cases} yz - 3\lambda = 0 \\ xz - 2\lambda = 0 \\ xy - \lambda = 0 \\ -(3x + 2y + z - 1) = 0 \end{cases} \quad (\Leftrightarrow)$$

$$\Leftrightarrow \begin{cases} xyz - 3\lambda x = 0 \\ xyz - 2\lambda y = 0 \\ xyz - \lambda z = 0 \\ 3x + 2y + z = 1 \end{cases} \quad (\Leftrightarrow) \begin{cases} -3\lambda x + 2\lambda y = 0 \\ -2\lambda y + \lambda z = 0 \\ = \\ = \end{cases} \quad (\Leftrightarrow)$$

$$\Leftrightarrow \begin{cases} \lambda(-3x + 2y) = 0 \\ = \\ = \end{cases} \quad (\Leftrightarrow) \begin{cases} \lambda = 0 \vee 3x = 2y \\ = \\ = \end{cases}$$

Se $\lambda = 0$ então

$$xyz = 0 \Leftrightarrow x = 0 \vee y = 0 \vee z = 0 \text{ não estando}$$

a caixa bem definida.

Assim,

$$\begin{cases} x = \frac{2y}{3} \\ \wedge (-2y + z) = 0 \\ = \end{cases}$$

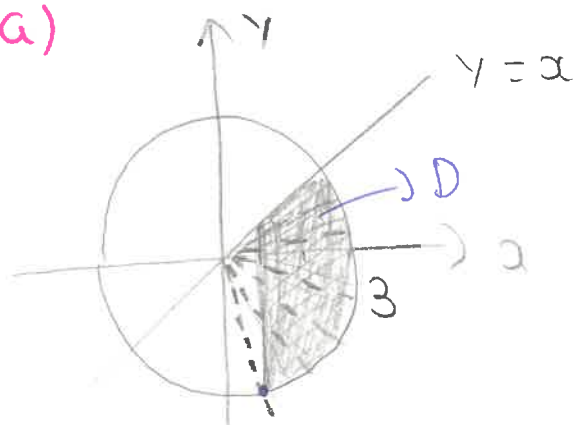
$$\Leftrightarrow \begin{cases} x = \frac{2y}{3} \\ z = 2y \\ 2y + 2y + 2y = 1 \end{cases}$$

$$\Leftrightarrow \begin{cases} x = \frac{1}{9} \\ z = \frac{1}{3} \\ y = \frac{1}{6} \end{cases}$$

$\therefore$ A interseção do vértice de raio ser $(\frac{1}{9}, \frac{1}{6}, \frac{1}{3})$

8)

a)



$$|x_{\text{ael}}| = r$$

$$\begin{cases} x = r \cos \theta - \cos(\frac{1}{3}) \leq \theta \leq \frac{\pi}{4} \\ y = r \sin \theta \quad \frac{1}{\cos \theta} \leq r \leq 3 \end{cases}$$

$$1 = 3 \cos \theta \Leftrightarrow \cos \theta = \frac{1}{3} \Leftrightarrow$$

$$\Leftrightarrow \theta = \arccos(\frac{1}{3})$$

$$x = 1 \Leftrightarrow r \cos \theta = 1 \Leftrightarrow r = \frac{1}{\cos \theta}$$

$$\text{Área} = \iint_D 1 \, dx \, dy =$$

$$= \int_{-\arccos(1/3)}^{\pi/4} \int_{\frac{1}{\cos \theta}}^3 r \, dr \, d\theta$$

6)

$$\begin{aligned}
 \text{Area} &= \int_{-\arccos(1/3)}^{\pi/4} \left[\frac{r^2}{2} \right]_{\frac{1}{\cos \theta}}^3 d\theta = \\
 &= \int_{-\arccos(1/3)}^{\pi/4} \frac{9}{2} - \frac{1}{2} \frac{1}{\cos^2 \theta} d\theta = \\
 &= \left[\frac{9}{2} \theta - \frac{1}{2} + \frac{1}{2} \tan \theta \right]_{-\arccos(1/3)}^{\pi/4} = \\
 &= \frac{9\pi}{8} - \frac{1}{2} + \frac{9}{2} \arccos(1/3) + \frac{1}{2} + \frac{1}{2} \tan(-\arccos(1/3)) \\
 &= \frac{9\pi}{8} - \frac{1}{2} + \frac{9}{2} \arccos(1/3) + \frac{1}{2} - \frac{2\sqrt{2}}{1/3} =
 \end{aligned}$$

$$x^2 + y^2 = 9 \Leftrightarrow 1 + y^2 = 9 \Leftrightarrow$$

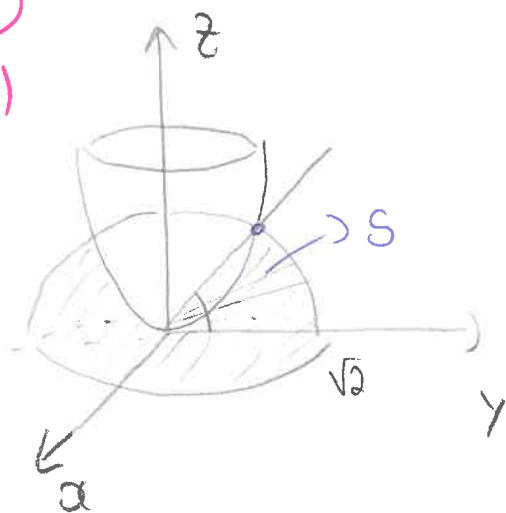
$$\Leftrightarrow y^2 = 8 \Leftrightarrow y = \pm 2\sqrt{2}$$

$$-2\sqrt{2} = 3 \sin \theta \Leftrightarrow \sin \theta = -\frac{2\sqrt{2}}{3}$$

$$= \frac{9\pi}{8} - \frac{1}{2} + \frac{9}{2} \arccos(1/3) - \sqrt{2}$$

(9)

a)



$$\begin{cases} x = \rho \cos \theta \sin \varphi \\ y = \rho \sin \theta \sin \varphi \\ z = \rho \cos \varphi \end{cases}$$

$$\frac{\pi}{4} \leq \varphi \leq \frac{\pi}{2}$$

$$0 \leq \theta \leq 2\pi$$

$$\frac{\cos \varphi}{\sin^2 \varphi} \leq \rho \leq \sqrt{2}$$

$$z = x^2 + y^2 \Leftrightarrow$$

$$\Leftrightarrow \rho \cos \varphi = \rho^2 \sin^2 \varphi \Leftrightarrow$$

$$\Leftrightarrow \rho \cos \varphi - \rho^2 \sin^2 \varphi = 0 \Leftrightarrow$$

$$\Leftrightarrow \rho (\cos \varphi - \rho \sin^2 \varphi) = 0 \Leftrightarrow$$

$$\Leftrightarrow \rho = 0 \vee \rho = \frac{\cos \varphi}{\sin^2 \varphi}$$

$$|Jae| = \rho^2 \sin \varphi$$

$$\begin{cases} z = x^2 + y^2 \\ x^2 + y^2 + z^2 = 2 \end{cases} \Leftrightarrow \begin{cases} z = - \\ z^2 + z - 2 = 0 \end{cases} \Leftrightarrow \begin{cases} z = -1 \pm \frac{\sqrt{1+8}}{2} \end{cases}$$

$$\Leftrightarrow \begin{cases} z = -1 \pm \frac{3}{2} \end{cases} \Leftrightarrow \begin{cases} z = -2 \vee z = 1 \end{cases}$$

$$1 = \sqrt{2} \cos \varphi \Leftrightarrow \cos \varphi = \frac{1}{\sqrt{2}} \Leftrightarrow \varphi = \arccos\left(\frac{1}{\sqrt{2}}\right) = \frac{\pi}{4}$$

$$\text{Volume} = \iiint_S 1 \, dx \, dy \, dz = \int_0^{2\pi} \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \int_{\frac{\cos \varphi}{\sin^2 \varphi}}^{\sqrt{2}} \rho^2 \sin \varphi \, d\rho \, d\varphi \, d\theta$$

(15)

b)

(16)

$$\text{Volume} = 2\pi \int_{\pi/4}^{\pi/2} \left[\frac{\rho^3}{3} \sin \varphi \right]_{\frac{\cos \varphi}{\sin^2 \varphi}}^{\sqrt{2}} d\varphi =$$

$$= \frac{2\pi}{3} \int_{\pi/4}^{\pi/2} 2\sqrt{2} \sin \varphi - \frac{\cos^3 \varphi}{\sin^6 \varphi} \sin \varphi d\varphi$$

$$= \frac{2\pi}{3} \int_{\pi/4}^{\pi/2} 2\sqrt{2} \sin \varphi - \frac{\cos^3 \varphi}{\sin^5 \varphi} d\varphi =$$

$$= \frac{2\pi}{3} \int_{\pi/4}^{\pi/2} 2\sqrt{2} \sin \varphi - \frac{1}{\sin^2 \varphi} \cot^3 \varphi d\varphi =$$

$$= \frac{2\pi}{3} \left[-2\sqrt{2} \cos \varphi + \frac{\cot^4 \varphi}{4} \right]_{\pi/4}^{\pi/2} =$$

$$= \frac{2\pi}{3} \left(2\sqrt{2} \frac{\sqrt{2}}{2} - \frac{1}{4} \right) = \frac{2\pi}{3} \left(2 - \frac{1}{4} \right)$$

$$= \frac{2\pi}{3} \left(\frac{7}{4} \right) = \frac{7\pi}{6}$$

(10) x_* é um ponto estacionário de f se $\nabla f(x_*) = 0$ (14)

Consideremos $-\nabla f(x_*)$. Damos que existem

$\alpha_1, \dots, \alpha_m \geq 0$ tais que

$$-\nabla f(x_*) = \sum_{i=1}^m \alpha_i v_i$$

$$-\nabla f(x_*)^T \nabla f(x_*) = \left(\sum_{i=1}^m \alpha_i v_i \right)^T \nabla f(x_*) =$$

$$= \sum_{i=1}^m \underbrace{\alpha_i}_{\geq 0} \underbrace{v_i^T \nabla f(x_*)}_{\geq 0} \geq 0$$

Mas

$$-\nabla f(x_*)^T \nabla f(x_*) = -\|\nabla f(x_*)\|^2 \leq 0$$

Logo

$$-\|\nabla f(x_*)\|^2 = 0 \Leftrightarrow \nabla f(x_*) = 0$$

Logo que x_* é um ponto estacionário de f .